Estimation of optimum velocity model and precise earthquake locations in NE Aegean: Implications for seismotectonics and seismic hazard

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ABSTRACT

This study relocates the seismicity in NE Aegean during the period 2011–2017 using data recorded by the Hellenic Unified Seismic Network (HUSN) in order to elucidate the relationship between seismicity and active faults in this area. P- and S-phase travel times of well-recorded events were first inverted in order to derive a minimum 1D velocity model with station delays using VELEST. Absolute locations of 4450 events were obtained by use of the nonlinear probabilistic algorithm NLLOC and the newly derived velocity model. Precise relative locations with horizontal and vertical uncertainties that do not exceed 1.2 km were calculated for 3354 events using the double-difference algorithm. The relocated seismicity delineates active faults to the south of Lesvos island, at the tip of Biga peninsula in Turkey and along the parallel strands of strike-slip faults that accommodate the westward motion of Anatolia. The comparison of the seismicity distribution with known active faults and the regional stress field shows that the strike-slip faults represent either principal shear zones, or Riedel shears oriented obliquely to the minimum stress axes. Normal faults are oriented almost perpendicular to the direction of the minimum stress axes in accordance with the transtensional deformation model. The seismogenic layer thickness derived from the depth distribution of relocated seismicity was found to be in the range of 14.8–15.8 km. By combining this thickness with geometrical characteristics of active faults and with a relationship that connects moment magnitude with rupture area, it is possible to estimate expected magnitudes of earthquakes. These magnitudes range from 6.3 to 7.2 depending on the rupture scenario that is considered for each fault. Of particular concern are the faults of Agia Paraskevi in Lesvos and Mastichochoria in Chios island that are densely populated areas and can produce large events with magnitudes from 6.4 to 6.9. Very little seismicity can be observed along these faults in the past 7 years, which may indicate either that they are creeping, or that they are locked and accumulate strain energy.

1. Introduction

The Aegean is an area of intense deformation as a result of the gravitational spreading of the Aegean lithosphere and the westward motion of Anatolia (Hatzfeld et al., 1997; Meijer and Wortel, 1997; Nyst and Thatcher, 2004; Hollenstein et al., 2008; Floyd et al., 2010; Konstantinou et al., 2016). In the northern part of the area, the North Aegean Trough forms a series of pull-apart sedimentary basins bounded by NE-SW oriented strike-slip faults that represent the different branches of the North Anatolian Fault in the Aegean (Papanikolaou et al., 2002; Koukouvelas and Aydin, 2002; McNeill et al., 2004; Beniest et al., 2016) (Fig. 1). To the south of the North Aegean Trough from the Turkish coast up to the island of Skyros, several other branches with the same orientation can be observed that delineate smaller pull-apart basins. While the kinematics of these faults exhibit dextral sense of motion, they are interrupted by NW-SE oriented sinistral strike-slip faults such as the ones to the north of Skyros island (cf. Fig. 1). These faults are thought to be older structures that became reactivated with a sinistral sense of motion under the present day stress field (Kiratzi, 2002). GPS observations confirm the notion that the faults bounding the North Aegean Trough accommodate most of the westward motion of Anatolia and that the faults to the south of it are less developed, as indicated by their smaller strain and slip rates (Kreemer et al., 2004; Müller et al., 2013).

Seismicity in the NE Aegean is quite high as suggested by several large (Mw > 6.0) earthquakes that have occurred during the last 73 years (Papazachos and Papazachou, 2003) (cf. Fig. 1 and Table 1). The majority of them have nucleated along the NE-SW oriented strike-slip faults, even though there are notable exceptions to this trend. The first of these exceptions is the 2001 Skyros (Mw ~ 6.4) earthquake that ruptured one of the older NW-SE oriented strike-slip faults (Karakostas et al., 2003; Roumelioti et al., 2003). The second exception has to do with...
with earthquakes that nucleated along normal rather than strike-slip faults (e.g. the 1967 Mw 6.6 Skyros earthquake), implying a rather complex seismotectonic regime for the NE and central Aegean. More recently this area experienced further seismic unrest, first during January-March 2017 when a swarm consisting of hundreds of events occurred at Biga peninsula, and then in June 2017 when a major earthquake (Mw ∼ 6.3) struck near the south coast of Lesvos island. The fact that most of these faults lie beneath the sea surface means that in situ observations are inadequate for resolving their characteristics. Seismological observations can be used instead in order to understand fault geometry and kinematics; however, for such an approach to be fruitful precise earthquake locations are needed that can delineate the faults both at shallow and deeper levels within the crust.

This work relocates the seismicity in NE Aegean motivated primarily by the need to understand the geometry and segmentation characteristics of active faults and to estimate the thickness of the seismogenic layer, all of which can help towards assessing seismic hazard in the area. First, a brief summary of the available data is given in terms of network configuration and routine data processing. A minimum 1D velocity model with station delays for P- and S-waves is then derived by inverting travel times of well-recorded events. Improved absolute and precise relative locations are calculated by using the newly derived optimum velocity model in an effort to accurately delineate the seismogenic sources that lie within the study area and correlate them to known active faults. Finally, the discussion focuses on the relationship of these seismogenic sources with the regional stress field and their potential to nucleate large earthquakes in the future.

2. Data

The Hellenic Unified Seismic Network (hereafter called HUSN) represents the permanent seismic network that monitors earthquake activity in the Aegean as well as in mainland Greece. HUSN is the result of the merging in 2008 of three networks operated by Greek universities (Athens, Thessaloniki and Patras) with the nationwide network...
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operated by the National Observatory of Athens (hereafter called NOA), Institute of Geodynamics. All HUSN stations are equipped with three-component sensors that are broadband up to 20–120 s depending on the sensor type (CMG-40 T, CMG-3ESP, Lennartz Le-3D, STS-1, STS-2, Trillium 120 P). The recorded waveforms are then relayed in real time to NOA headquarters where events are routinely located by NOA staff after phase picking and assignment of quality weights to each pick. The NOA catalog was searched from January 2011 until December 2017 in order to find events within an area that covers the western Turkish coast up to the Greek island of Skyros (cf. Fig. 1). The use of data recorded during the period 2011–2017 has two main advantages: first, during this period HUSN exhibits the best quality and largest quantity of recordings since its initiation; and second, this period includes intense seismic activity that can give important hints in relation to the regional tectonics. The search yielded a total of 4,450 events that were recorded by 8 or more stations. Most of these events had local magnitudes smaller than 3.0, essentially representing microseismicity, six of them had local magnitude between 5.0–5.5, and the 12 June 2017 Lesvos earthquake was the largest event during this period. The study area is surrounded by 30 HUSN stations that offer good azimuthal coverage as can be seen in Fig. 1. An additional number of 5 strong-motion sensors whose phase picks can also be used, increases the available stations to 35 and fills some of the remaining azimuthal gaps.

3. Minimum 1D velocity model

A minimum 1D velocity model can be defined as the velocity model that produces the smallest possible uniform error for a set of events with well-constrained locations (Kissling et al., 1994). The software package VELEST (Kissling, 1995) estimates such a model by simultaneously inverting P- and S-wave travel times for a 1D velocity model, hypocentral locations and station delays. VELEST first solves the forward problem by tracing direct, reflected and refracted rays from source to receiver, and standard damped least squares is used in order to solve the inverse problem. For the purpose of applying this methodology to the dataset from NE Aegean, suitable events have to be selected that conform to the following criteria: (a) the number of P- and S-phases should be more than 15, (b) the azimuthal gap should be less than 180°, and (c) the RMS residual value should be less than 0.4 s. A total of 418 events were found to be in accordance with these criteria, yielding 5585 P-phases and 2446 S-phases. Station LIA (25.1805°, 39.89702°), placed on molasses deposits, was selected as the reference station since it recorded one of the largest number of phases and it is located near the center of the network. VELEST does not automatically adjust the thickness of the model layers after each iteration, therefore the initial model was parameterized with thickness equal to 2 km for the layers at the top 20 km and 5 km for the layers deeper than that.

As with all inverse problems, obtaining a minimum 1D velocity model relies on finding a robust minimum in the solution space rather than a local one. In order to explore as much as possible the model space, a series of 60 initial models were constructed whose velocities were subjected to the constraint not to contain low velocity layers. At first, only P-wave travel times were inverted for the reason that P-phases provide better spatial sampling and involve smaller picking errors. Fig. 2 shows the 60 initial models and also the 12 final models that exhibited the lowest RMS residual (~0.29 s). It can be seen that these models become very similar in the depth interval 5–20 km, while they display more variation at 20–35 km and at the top 5 km. This variation can be easily explained by considering that ray density significantly decreases below 20 km, which results in unconstrained velocities for these depths, and that rays at the top 5 km are almost vertical and thus do not sample the medium adequately. The final P-wave velocity model is then taken as the average of these 12 models and subsequently S-phase travel times were also inverted in order to derive the minimum 1D S velocity model. The final P and S velocity models as well as the variation of the Vp/Vs ratio as a function of depth can be seen in Fig. 3.

A comparison of the P velocity model with the velocity model derived by Akyol et al. (2006) for western Anatolia shows a good agreement, with the model derived in this study being 4%–5% faster in the interval 10–20 km. These faster velocities may indicate that the crust in the NE Aegean is cooler, less fractured and/or more dry than the crust in the adjacent area of western Anatolia. Similarly, the S velocity model agrees relatively well with the shear wave velocity profile obtained from inversion of Rayleigh waves in NE Aegean (Karagianni et al., 2005).

One way to evaluate the robustness of the newly derived minimum 1D model is to randomly shift by some amount the initial hypocentral coordinates of the events before the inversion. If the proposed model is indeed a robust minimum in the solution space, the events will be relocated back to their previous positions and no significant changes in velocity will occur. This test was performed by perturbing the location coordinates of the input events by ±7 km and then use VELEST to invert for event locations and P, S velocity model. It was found that the average difference between the original and recalculated locations was 20 m (±200 m) in latitude, 250 m (±430 m) in longitude and 1.3 km (±1.2 km) in depth. The recalculated P, S velocity model is very close to the original, except from the top 5 km (Fig. 4). Another test that can be used to infer the reliability of the proposed model is to examine whether the station delays are in accordance with the near-
surface geology at each station site. The stations included in this study are placed on three kinds of sites, namely soft rock (shists, tuffs), hard rock (limestone, marble, granite, lavas) and alluvium deposits. It can be seen that stations placed on hard rock exhibit negative delays (especially for P-waves), while stations placed on soft rock or alluvium deposits have almost zero or positive delays (Fig. 5). This means that the inverted delays correctly identify stations whose site exhibit higher true velocities (i.e. negative values) or lower true velocities (i.e. positive values) than the minimum 1D model.

4. Absolute locations

Using the newly derived minimum 1D model with station delays it is possible to estimate improved absolute locations for the events within the study area. Rather than utilizing linear approximations for solving the earthquake location problem, the freely available software package NLLOC (Lomax et al., 2000, 2009) is used instead. NLLOC employs a nonlinear probabilistic algorithm that calculates earthquake locations after reconstructing the posterior probability density function (PDF) (e.g. Tarantola and Valette, 1982; Moser et al., 1992) through the sampling of the solution space using the Oct-tree search algorithm (Lomax and Curtis, 2001). The maximum likelihood point of the complete posterior PDF is then considered to be the sought earthquake location. NLLOC also offers the option of using the Equal Differential-Time (EDT) function (Font et al., 2004) as the likelihood function to be maximized, which is formed from the differences of residuals recorded at pairs of stations. The advantage of combining the PDF formulation along with the EDT likelihood function is the ability of estimating robust locations even if the observed travel times contain large outliers.

A 3D grid consisting of 500 × 500 × 180 cells with node spacing of 1 × 1 × 1 km was employed in order to pre-calculate theoretical travel times for each station using the finite differences algorithm of Podvin and Lecomte (1991). Location uncertainties in the horizontal and vertical directions were calculated by using the diagonal elements of the covariance matrix (see Maleki et al., 2013). These elements are sensitive to the shape of the PDF and become large when this shape starts deviating from quasi-ellipsoidal, signifying a decrease in the location accuracy. Fig. 6 shows the locations of all events in the study area obtained with NLLOC by using the P and S minimum 1D model with station delays. Significant seismicity can be observed along the south coast of Lesvos island, partly due to the strong earthquake in June 2017, extending towards the Karaburun peninsula. A large number of events seems to be concentrated along the northern coast of Chios island and smaller clusters appear to the north and south of the island of Psara. North of Lesvos, at the tip of the Biga peninsula, a large cluster consisting of hundreds of events represents the swarm activity that occurred during January-March 2017. Clusters of events exhibiting a linear distribution can be seen to extend from the Turkish coast to the south of Agios Efstratios island and to the south of Skyros island.

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Average horizontal uncertainty was found equal to 3.7 km (± 3 km) while the average vertical uncertainty is 4.8 km (± 2.4 km). Uncertainties increase significantly at longitudes east of 26.5° (i.e. Karaburun peninsula) that are areas outside HUSN, where the closest station is located 50 km away (cf. Fig. 1).

It is interesting to compare the probabilistic nonlinear locations with the routine ones of the NOA catalog in order to assess their differences. In terms of the RMS residual, the use of NLLOC and the minimum 1D model has decreased the average value from 0.38 s in NOA locations to 0.30 s, which implies a reduction of about 21%. The distribution of the RMS residuals for the two kinds of locations appears similar in shape, with a heavier tail at larger values for the distribution...
of the NOA locations (Fig. 7a). Epicentral locations were found to agree quite well with differences of less than 1 km in most cases; however, this is not the case for hypocentral depths. As can be seen in Fig. 7b, the depth distribution of NLLOC locations shows that the majority of events nucleated at the top 15 km of the crust and that after this the number of events decreases sharply. This is consistent with the crustal thickness of 25–28 km in the Aegean area (Sodoudi et al., 2006) and a rheology compatible with a brittle upper crust on top of a progressively more ductile lower crust (Konstantinou, 2010). On the other hand, the depth distribution of NOA locations mirrors the NLLOC depth distribution up to about 20 km; instead of decreasing in numbers however, a new peak appears at 28 km and more events are contained at bins deeper than 30 km. This bimodal depth distribution in NOA locations has been also found in a recent study of the seismicity along the North Aegean Trough (Konstantinou, 2017). Synthetic location tests performed in that study had shown that abnormally deep hypocenters may be the result of the relatively simple velocity model used by NOA staff for the location process. The rather low RMS residuals of NOA locations also point to the possibility that stations with large residuals are probably down-weighted by NOA staff in an effort to obtain better location statistics, resulting to a systematic overestimation of the hypocentral depth.

5. Relative locations

5.1. Method

Earthquake locations can be further improved with the calculation of precise relative locations using the double-difference algorithm (also known as HYPODD) developed by Waldhauser and Ellsworth (2000). The algorithm utilizes differential travel times calculated either from catalog data or cross-correlation of waveforms in order to minimize the time residual of pairs of events by adjusting the difference in their hypocentral distance. In this study, the requirements for calculating differential travel times involved a separation distance of 10 km for source-receiver distances up to 400 km and that each event connected with 10 other of its neighbors. Following the suggestion of Waldhauser (2001), at least 8 phase pairs are needed in order to consider that neighboring events are strongly linked. From the initial 4,450 events a total of 4,187 were finally selected forming a network of links with 450,015 P-phase and 224,499 S-phase pairs. Most of the events...
that were rejected actually fall east of longitude 26.5°, where uncertainties in absolute locations were found to be more than 5 km. The number of average links per event pair was 10 having an average offset between linked events of 4.4 km, while only a small percentage (≈ 2%) of outliers was found. HYPODD uses a 1D P-wave velocity model and a constant Vp/Vs ratio in order to calculate theoretical differential travel times for the P and S phases. For the purposes of this study the P-wave minimum 1D model along with a Vp/Vs ratio of 1.73 were utilized in the relocation. Due to the large number of events the relocation problem was solved by using the LSQR method of dumped least-squares. The damping factor was set to 60 by applying the rule of thumb that condition numbers should be between 40–80 for most of the event clusters (Waldhauser, 2001). As in previous HYPODD relocations with HUSN data (e.g. Roumelioti et al., 2003; Konstantinou, 2017) the a priori weights were set to 1.0 for P-phases and 0.5 for S-phases; reweighting was allowed after the first 6 iterations by placing more weight on small inter-event distances. In this way, 3,354 events were finally relocated that represent about 80% of the initially selected events. The average RMS residual dropped after the relocation to 0.06 s (± 0.08 s) that represents a significant reduction compared to the average RMS residual of NLLOC (≈ 0.30 s) and NOA (≈ 0.38 s) locations. Uncertainties of the relocated events were assessed by relocating smaller clusters using the Singular Value Decomposition (SVD) method. Relative horizontal uncertainties reach a value of up to 1.2 km, while the relative vertical ones do not exceed 0.8 km as summarized in Table 2. In what follows, the relocation results are combined with routine focal mechanism solutions provided by NOA and other agencies in order to jointly interpret fault geometry and kinematics.

5.2. Results

5.2.1. Offshore southern Lesvos

The relocated seismicity in the area between Lesvos and Chios islands is dominated by the 12 June 2017 (Mw ~ 6.3) earthquake and its aftershocks (Fig. 8). Expansion of the aftershock area resulted in a zone with a length of about 40 km by the end of December 2017, which is almost double of what would be expected for an earthquake of this magnitude. The mainshock was relocated to the SE of Lesvos (at 38.8695°, 26.3497°) at a hypocentral depth of 12.6 km and exhibited a magnitude. The mainshock was relocated to the SE of Lesvos (at 39.809 26.101 16.95 0.09 0.03 0.11 2 43 38.696 25.499 13.55 0.31 0.26 0.55 1 62 39.411 25.93 6.59 1 1.2 0.8

Anatolian Fault within the Aegean. Indeed, the relocated seismicity –100 cm) coincides with an area free of any aftershocks. The focal location of the swarm coincides spatially with the actively exploited Tuzla geothermal field, put forward the suggestion that the swarm may represent an example of induced seismicity.

5.2.2. Biga peninsula-northern Lesvos

The seismic activity at Biga peninsula started in early January 2017 with small magnitude (M<sub>n</sub> < 3.0) earthquakes that culminated in the generation of four moderate magnitude (Mw ~ 5.0–5.2) events in February 2017. Two of these events occurred on 6 February (at 03:51:41 and 10:58:02 UTM respectively), the third one occurred the next day (07/02) and the fourth on 12 February. The activity continued with numerous smaller earthquakes throughout March and started declining from early April, however, events continued to occur sporadically until December 2017. Reported focal mechanisms indicate pure normal faulting along NW-SE direction. Fig. 9 shows the relocated seismicity at Biga peninsula and offshore northern Lesvos where it can be seen that the epicentral locations indeed form a NW-SE cluster that covers the tip of the peninsula and extends offshore towards NW. The seismicity looks more scattered in the area between the Turkish coast and the northern coast of Lesvos without exhibiting any clear correlation with known faults. The two perpendicular depth cross-sections give a sharp image of the fault geometry, depicting a curved listric fault that dips towards SW, extending from a depth of about 3 km down to 17 km. Cross-section BB' also reveals that an antiathetic fault, dipping towards NE, was activated almost at the same time even though it only generated small magnitude events. The first three moderate magnitude events are well-aligned along the curved surface of the fault, with the first (06/02 at 03:51) nucleating at a depth of 12 km, the second (06/02 at 10:58) at 14 km and the third (07/02) at 16 km. This spatio-temporal sequence implies that the rupture propagated progressively downwards within a period of 2 days. The dipping of the fault planes support this spatio-temporal relationship, since the dip angle changed from 50° for the first event to 38° for the second and 34° for the third and deepest event. The fourth event (12/02) is located further to the east at a depth of 6 km and is probably the result of stresses within the shallow crust induced by the three earlier events. It should be noted that the steep shallow part of the activated listric fault and its antimhetic agree with field observations that show high-angle normal faulting being a major seismotectonic feature in the Biga peninsula (Sözüбли et al., 2016). Deep cross-section AA' along the ruptured surface shows two large clusters of events that combine to define a fault with a total length of 17 km. Seismicity that occurred prior to 2017 appears to be evenly distributed among different depths as shown in the depth cross-sections and seems to envelope the area that ruptured during the swarm. The downward propagation of the rupture, coupled with the fact that the location of the swarm coincides spatially with the actively exploited Tuzla geothermal field, put forward the suggestion that the swarm may represent an example of induced seismicity.

5.2.3. Skiros-Edremit zone

The line that connects Edremit Gulf with the island of Skiros coincides with the orientation of the different branches of the North Anatolian Fault within the Aegean. Indeed, the relocated seismicity along this line exhibits elongated clusters that mostly coincide with strike-slip faults that exist in this area (Fig. 10). The majority of these
events have local magnitudes smaller than 3.5 and only two events, one on 8 January 2013 and another on 11 October 2017 have larger magnitudes. The former event was the largest (Mw ≈ 5.6) and was located at the edge of the fault that produced the 1968 Agios Efstratios earthquake. It was followed by numerous aftershocks distributed along the fault plane as well as along parallel strands (for details see Karakostas et al., 2014; Ganas et al., 2014). The latter event was a moderate one (Mw ≈ 5.0) located at the NW of Skyros and it nucleated along the same fault that produced the 2001 strong earthquake (cf. Table 1 and Fig. 1).

Depth cross-section AA' covers the area along Skyros island where it can be seen that the majority of the relocated earthquakes occur at the edges of the main slip patch of the 2001 earthquake (cf. Fig. 10). The other depth cross-section (BB') runs along the main NE-SW branch of the North Anatolian Fault, part of which ruptured on 19 December.

Fig. 8. Upper panel: Map showing the distribution of relative locations for the area of southern Lesvos-northern Chios. The green star indicates the location of the 12 June 2017 Lesvos earthquake. Circles correspond to aftershocks while diamonds represent events that occurred prior to the Lesvos earthquake. Beach balls represent focal mechanism solutions of aftershocks taken from the moment tensor database of NOA, Institute of Geodynamics. The grey beach ball indicates the focal mechanism solution for the largest aftershock. The panel at the right hand side lists the focal mechanism solutions of the mainshock that were reported by various groups/agencies. Lower panel: Depth cross-sections corresponding to the profiles shown on the map. Blue circles are aftershocks while red diamonds are events prior to the 12 June 2017 earthquake. Dashed black lines outline the orientation of inferred fault planes. Solid black ellipses represent slip contours of the patch that ruptured during the mainshock obtained from the study of Kiratzi (2018). (For interpretation of the references to colour in this figure legend, the reader is referred to the web version of this article).
1981 during a strong (Mw $\sim 6.8$) earthquake (cf. Table 1 and Fig. 1). The seismicity defines linear features at the SW and at the NE part of this fault, effectively encompassing the segment that ruptured in 1981. This segment seems to be devoid of any earthquakes and has a length of about 43 km (cf. Fig. 10). Other smaller clusters appear to the north and south of the island of Psara and coincide with known active faults. The available focal mechanisms confirm the dominance of strike-slip faulting in the area (along NE-SW or NW-SE directions), but normal faulting events along the WNW-ESE direction are also present.

Fig. 9. Upper panel: Map showing the distribution of relative locations for the area of Biga peninsula-northern Lesvos. The green stars indicate the locations of the four moderate events that occurred in January-February 2017. Circles correspond to events of the January-March 2017 swarm, while diamonds are events that occurred prior to 2017. Beach balls represent focal mechanism solutions of aftershocks taken from the moment tensor database of NOA, Institute of Geodynamics. Lower panel: Depth cross-sections corresponding to the profiles shown on the map. Blue circles are hypocenters of swarm events and red diamonds are hypocenters of events that occurred prior to 2017. (For interpretation of the references to colour in this figure legend, the reader is referred to the web version of this article).
6. Discussion

6.1. Seismicity and regional stress

The precise location of seismicity in NE Aegean offers the opportunity to compare it with known active faults and also to examine its relationship with the regional stress field. Fig. 11 shows the traces of active faults included in the GReDaSS database (Caputo and Pavlides, 2013) and their sense of motion based on kinematic indicators such as focal mechanisms. The Figure also includes faults that were found to be seismically active during the period of this study but are not included in GReDaSS. The present-day stress field in the Aegean and mainland Greece has been recently derived by Konstantinou et al. (2016) after a damped inversion of a large number of focal mechanisms along a regular grid with a node spacing of 0.35°. A significant property of these stress inversion results is that they only contain the degree of spatial variation that is strongly required by the data. The orientations of the minimum stress axes for each node are superimposed on the other
features in Fig. 11, while their plunge angle ranges between 5°–10°. Uncertainties in both orientation and plunge angle of the stress axes did not exceed 10° and were inferred by using a bootstrap resampling technique. The dominant structural feature in Fig. 11 is the parallel strands of dextral strike-slip faults that accommodate the westward motion of the Anatolian plate. These strands essentially represent principal shear zones that form obliquely to the minimum stress axes, followed occasionally by P or R Riedel shears. The NW-SE strike-slip faults with sinistral motion are intersected by the minimum stress axes at a high angle and therefore may correspond to R’ Riedel shears. Normal faults can form with a strike nearly perpendicular to the minimum stress axes, as exemplified by the 12 June 2017 Lesvos earthquake and the Biga peninsula events. Such a transtensional deformation pattern can be attributed to the combined effect of the Anatolian westward push and the gravitational spreading of the Aegean plate caused by slab rollback along the Hellenic subduction zone (Meijer and Wortel, 1997; Konstantinou et al., 2016).

6.2. Implications for seismic hazard

The hypocenters derived in this study can also be utilized for inferring the seismogenic layer thickness, which is an important parameter for estimating expected earthquake magnitudes along specific faults. As noted previously by Wyss (1979), fault length alone cannot provide accurate estimates of expected magnitude for the reason that the amount of elastic energy released during an earthquake also depends on the fault width. In this sense, scaling relationships that connect moment magnitude \( M \) with rupture area \( A \) are the most appropriate for evaluating the seismogenic potential of faults in NE Aegean. Konstantinou (2014) developed such relationships for earthquakes in the Mediterranean region and found that when \( A > 251 \text{ km}^2 \) the moment magnitude is given by

\[
M = \left(\frac{4}{3}\right) \log A + 3.07
\]

Using the value of seismogenic layer thickness \( H \) it is possible to estimate the fault width as \( W = H / \sin \delta \) where \( \delta \) is the dip of the particular fault and \( A \) is then equal to the product \( L \times W \), where \( L \) is the length of the fault. Fig. 12 shows the depth distribution for the Lesvos-Chios, Biga peninsula and Skyros-Edremit zone that contain the bulk of the relocated events. The onset and cutoff depths of the seismicity are calculated for each distribution as the 5th and 95th percentile, respectively. The difference of these two values is taken as the seismogenic layer thickness \( H \), which seems to be very similar in all three areas (14.8–15.8 km). As an example of this procedure, it is possible to estimate the moment magnitude of the 19 December 1981 earthquake mentioned earlier. For this fault \( L = 43 \text{ km} \) and \( W = 15.8 / \sin(90°) \) yielding a rupture area \( A = 679 \text{ km}^2 \). It can be easily verified that \( M = 6.8 \) which is consistent with the moment magnitude reported in the ISC-GEM catalog (Storchak et al., 2013). Using the 10th and 90th percentile as onset/cutoff depths for the estimation of \( H \) would only slightly change the magnitude value (\( M = 6.7 \)). On the other hand, an overestimation would occur in the case when the 1st and 99th
percentiles were used, yielding $H = 22.2\,\text{km}$ and $M = 7.0$.

There are four faults within the study area that can be considered as the most likely sites for future strong earthquakes, these are namely the Agia Paraskevi Fault (APF) in Lesvos island, the Edremit Fault (EF) along the southern coast of the Biga Peninsula, the Chios-Oinouses (COF) and Mastichochoria Fault (MF) in Chios island (cf. Fig. 11). All of these faults have produced in the past strong earthquakes with magnitudes larger than 6.0, while the time period since the last earthquake varies among them between 69 and 151 years. Geometrical characteristics of these faults are known from published studies such as Chatzipetros et al. (2013) for APF, COF, MF and Sözblir et al. (2016) for EF. When estimating expected magnitudes for APF and COF different rupture lengths are considered in order to take into account the uncertainties in their total length. Table 3 gives a summary of these fault characteristics as well as the expected magnitude in each case. Despite the fact that EF and COF are capable of producing large earthquakes with magnitudes from 6.7 to 7.2, the period since the last strong event in either fault is likely too short (69–74 years) for allowing the nucleation of another major earthquake within the next few years. On the contrary, APF and MF have both been seismically silent for over 100 years, therefore the discussion that follows will focus on these two faults.

APF is a strike-slip fault thought to be responsible for a strong earthquake on 7 March 1867 that caused 550 casualties in Lesvos island. The Edremit Fault (EF) is located in the southern coast of the Biga Peninsula, the Chios-Oinouses (COF) and Mastichochoria Fault (MF) in Chios island (cf. Fig. 11). All of these faults have produced in the past strong earthquakes with magnitudes larger than 6.0, while the time period since the last earthquake varies among them between 69 and 151 years. Geometrical characteristics of these faults are known from published studies such as Chatzipetros et al. (2013) for APF, COF, MF and Sözblir et al. (2016) for EF. When estimating expected magnitudes for APF and COF different rupture lengths are considered in order to take into account the uncertainties in their total length. Table 3 gives a summary of these fault characteristics as well as the expected magnitude in each case. Despite the fact that EF and COF are capable of producing large earthquakes with magnitudes from 6.7 to 7.2, the period since the last strong event in either fault is likely too short (69–74 years) for allowing the nucleation of another major earthquake within the next few years. On the contrary, APF and MF have both been seismically silent for over 100 years, therefore the discussion that follows will focus on these two faults.

APF is a strike-slip fault thought to be responsible for a strong earthquake on 7 March 1867 that caused 550 casualties in Lesvos island and the neighboring Turkish coast. Macroseismic as well as geochemical ascriptions only when the fault length did not exceed 20 km (Mw $\sim 6.4$), favoring a rupture that extends only onshore. The first scenario therefore considers that only the onshore segment of the fault ruptures; a second scenario assumes that the segment that ruptures includes the whole length of the Kalloni Gulf; and the third one deals with the rupture of both onshore and offshore segments. Expected moment magnitudes for these scenarios range from 6.4 to 6.9. On the other hand, MF is a strike-slip fault that is likely related to the 3 April 1881 Chios-Cesme earthquake which was the deadliest event to strike this area with more than 3500 casualties (Papazachos and Papazachou, 2003; Altinok et al., 2005). Assuming a rupture along its total length, the expected moment magnitude is 6.4, a value which agrees well with the magnitude of the 1881 event proposed by Papazachos and Papazachou (2003). At this point it should be mentioned that Chatzipetros et al. (2013) suggest that another fault, the Philadelphia Fault (PF) may also be a candidate source for the 1881 earthquake. The trace of this fault is parallel to the south coast of Chios island (cf. Fig. 11) and it may correspond to a normal fault based on a steep scarp seen in the shoreline morphology. The expected magnitude of a potential earthquake along PF is 6.3, only slightly lower than MF.

A general observation is that very few earthquakes were located during the study period along APF and almost none along MF (cf. Figs. 6, 8 and 9). This cannot be attributed to the completeness of the NOA catalog, since it has been found that seismicity recorded by HUSN in NE Aegean is complete down to magnitude 2.0 (D’Alessandro et al., 2011). Lack of seismicity may hence signify either that these faults are experiencing aseismic creep, or that they are locked and thus accumulate strain energy. Indeed, this is in accordance with the observation that in the Aegean area geodetic strain rates constrained by GPS data, are higher than the seismic ones calculated by using historical earthquake catalogs (see for example Rontogianni, 2010). Considering the seismogenic potential of these faults and that they traverse densely populated areas, it is of crucial importance that both of them are closely monitored so as to understand their deformation behavior.

### Table 3

<table>
<thead>
<tr>
<th>Fault</th>
<th>L (km)</th>
<th>$\delta$</th>
<th>W (km)</th>
<th>A ($\text{km}^2$)</th>
<th>M</th>
<th>T (years)</th>
</tr>
</thead>
<tbody>
<tr>
<td>APF (onshore)</td>
<td>20</td>
<td>90$^\circ$</td>
<td>15.8</td>
<td>316</td>
<td>6.4</td>
<td>151</td>
</tr>
<tr>
<td>APF (offshore)</td>
<td>32</td>
<td>90$^\circ$</td>
<td>15.8</td>
<td>505</td>
<td>6.7</td>
<td>151</td>
</tr>
<tr>
<td>APF (both)</td>
<td>52</td>
<td>90$^\circ$</td>
<td>15.8</td>
<td>821</td>
<td>6.9</td>
<td>151</td>
</tr>
<tr>
<td>EF</td>
<td>75</td>
<td>63$^\circ$</td>
<td>16.6</td>
<td>1245</td>
<td>7.2</td>
<td>74</td>
</tr>
<tr>
<td>COF (scenario 1)</td>
<td>30</td>
<td>60$^\circ$</td>
<td>18.2</td>
<td>546</td>
<td>6.7</td>
<td>69</td>
</tr>
<tr>
<td>COF (scenario 2)</td>
<td>58</td>
<td>60$^\circ$</td>
<td>18.2</td>
<td>1055</td>
<td>7.1</td>
<td>69</td>
</tr>
<tr>
<td>MF</td>
<td>20</td>
<td>87$^\circ$</td>
<td>15.8</td>
<td>316</td>
<td>6.4</td>
<td>137(*)</td>
</tr>
<tr>
<td>PF</td>
<td>17</td>
<td>80</td>
<td>16</td>
<td>272</td>
<td>6.3</td>
<td>137(*)</td>
</tr>
</tbody>
</table>

Scenario 1: only the segment parallel to the northern coast of Chios ruptures. Scenario 2: the rupture also extends to the Turkish coast. (*) These are the two candidate faults responsible for the 3 April 1881 Chios-Cesme event.

### 7. Conclusions

This study utilized the recorded seismicity in the NE Aegean during 2011–2017 in order to derive a minimum 1D velocity model with station delays and to obtain precise relative locations that delineate active faults in the area. The main conclusions of this work can be summarized as follows:

1. Improved absolute locations of 4450 events were obtained using the nonlinear probabilistic algorithm NLLOC and the newly derived velocity model with station delays. Estimated uncertainties were found to be less than 5 km both horizontally and vertically, however, east of longitude 26.5° these uncertainties increase significantly. A comparison of these improved locations with the routine ones provided by NOA showed differences in hypocentral depth distribution that are most likely caused by the simplified velocity model used in routine analysis and down-weighting of stations with large RMS residuals.

2. Precise relative locations of 3354 events were obtained by using the double-difference algorithm HYPODD, resulting in location uncertainties of 1.2 km or less both horizontally and vertically. The relocated seismicity delineates the normal fault that produced the 12 June 2017 Lesvos earthquake and also the listric fault that was activated during the January-March 2017 earthquake sequence at Biga Peninsula. Linear strands of strike-slip faults along the Skyros-Edremit zone were also delineated, as well as a 43 km segment that is devoid of any earthquakes and corresponds to the rupture zone of the 19 December 1981 (Mw $\sim 6.8$) earthquake in the central Aegean.

3. The seismotectonic pattern in this area can be explained in terms of transtensional deformation as a result of the combined westward push of the Anatolia plate and the gravitational spreading of the Aegean lithosphere. This leads to the development of principal shear zones along with P, R, R’ Riedel shears and normal faulting perpendicular to the direction of the minimum stress axes.

4. The seismogenic layer thickness in NE Aegean, expressed as the difference between the 5th and 95th percentile of the hypocentral depth distribution, is between 14.8–15.8 km. Based on these values and geometrical characteristics of faults in the area, the expected moment magnitude of potential earthquakes is estimated in the range of 6.4–7.2 depending on the choice of rupture scenario. Of particular concern are the faults of Agia Paraskevi in Lesvos and Mastichochoria in Chios that are thought to be responsible for strong earthquakes in 1867 and 1881 respectively. These two faults appear almost aseismic, an observation that can be interpreted either as a...
sign of creeping, or as a sign that they are locked and accumulate strain energy. Continuous seismic and geodetic monitoring is needed in order to investigate which of these two interpretations is valid.

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References


