



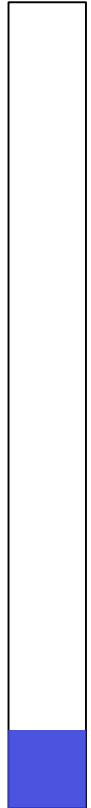
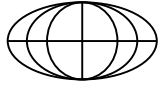
# Integration of multiple geospatial information for engineering applications

Prof. Jen-Yu Han

Professor, Civil Eng. Dept. National Taiwan University

Deputy Director, NCREE-NTUCE Joint AI Research Center

Director, Center for Research on High-performance Remote Sensing & Urban Informatics



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| **Evolution of Sensing Technology**

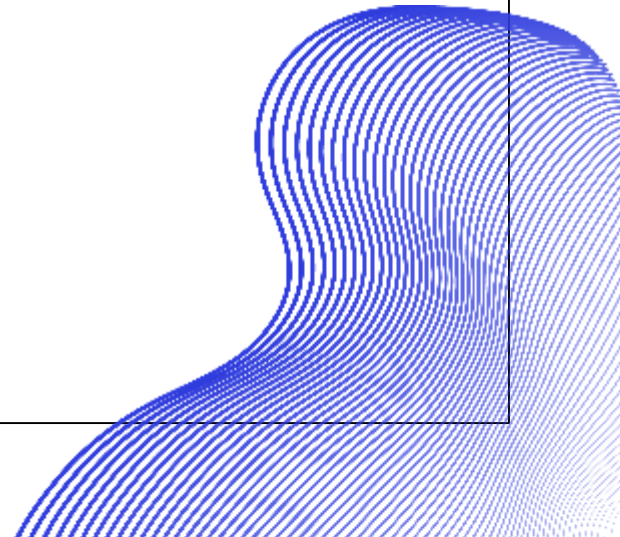
**02**

| **Artificial Intelligence**

**03**

**Practical Applications**

| UAV Application  
| SAR Application





# 01 Evolution of Remote Sensing



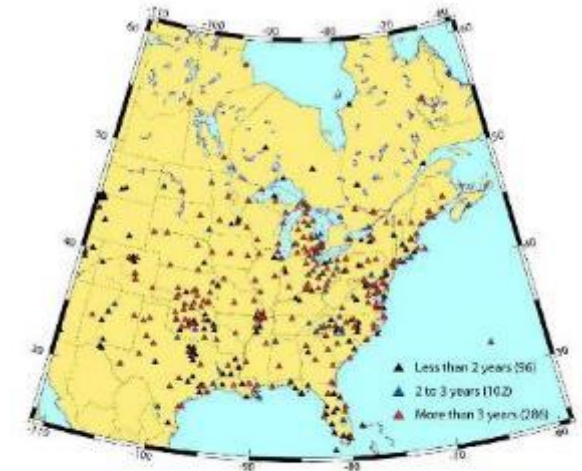
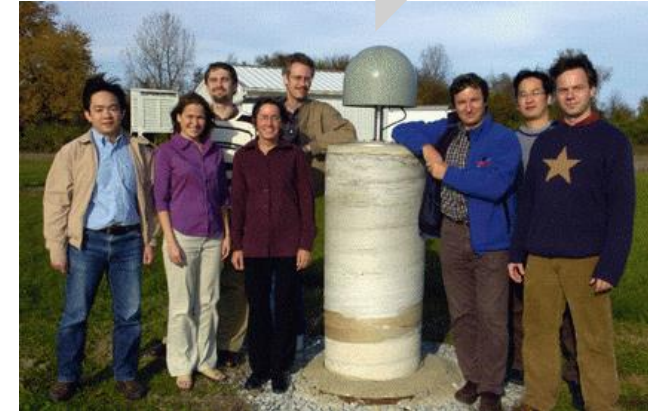
## Master's Study

- Year: **1996 – 1998.**
- Topic: **Analysis of Nuclear Power Plant Subsidence.**
- Data Collection: Levels & Total Stations.
- Data Frequency: **150 points x per season.**
- Analysis Method: Fortran 77, free network adjustment, each calculation takes approximately 10 seconds.



## PhD Study

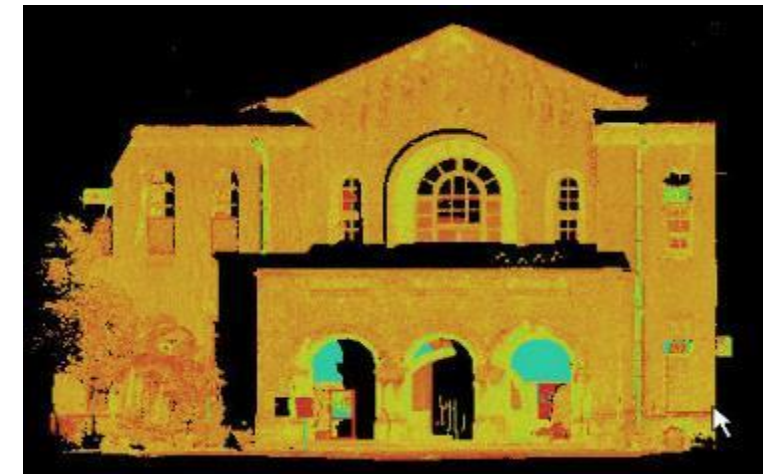
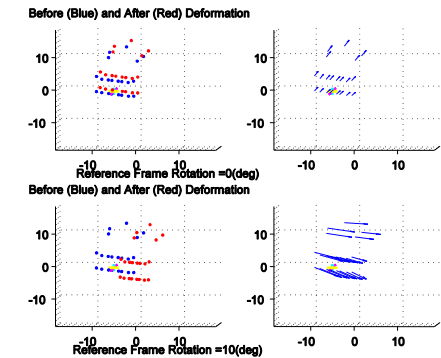
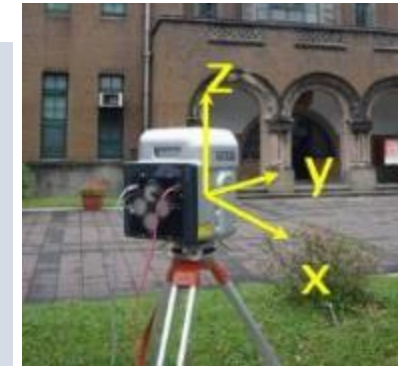
- Year: **2002 – 2006.**
- Topic: **Application of Continuous GPS Technique in Observing Surface Deformations.**
- Data Collection: Continuous GPS(CGPS) Stations.
- Data Frequency: **563 stations x per second (48 million entries/day).**
- Analysis Method: Linux Script, coordinate & velocity analysis, approximately 2-3 hours required to process one day's (24 hours) observation data.



563 continuous GPS sites: most are "CORS" stations + IGS + NRCan + local networks (e.g., GAMA)

Early period after returning to Taiwan

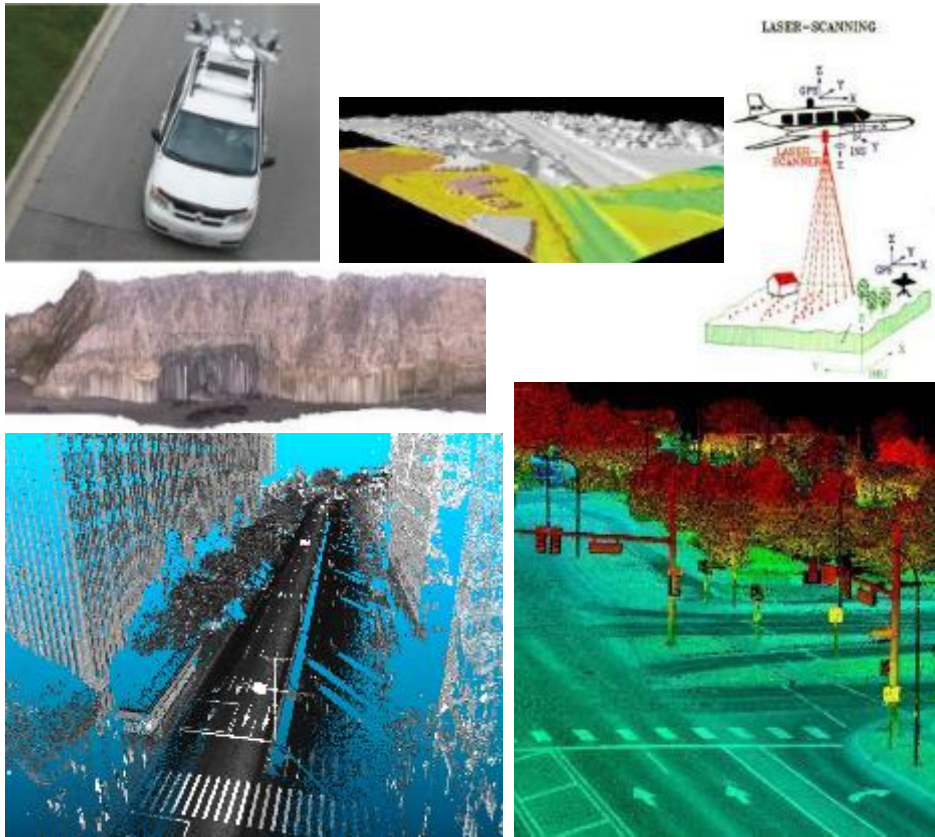
- Year: **2007 ~**
- Topic: **Monitoring Building Displacement using LiDAR Point Cloud.**
- Data Collection: MENSIS GS200 Laser Scanner.
- Data Frequency: **500 points per second (500Hz).**
- Analysis Method: MATLAB Script, tensor algorithm for feature extraction, approximately 2 - 3 hours processing time for 3 million points.



# 01 Evolution of Sensing Technology

NOW (2015 ~)

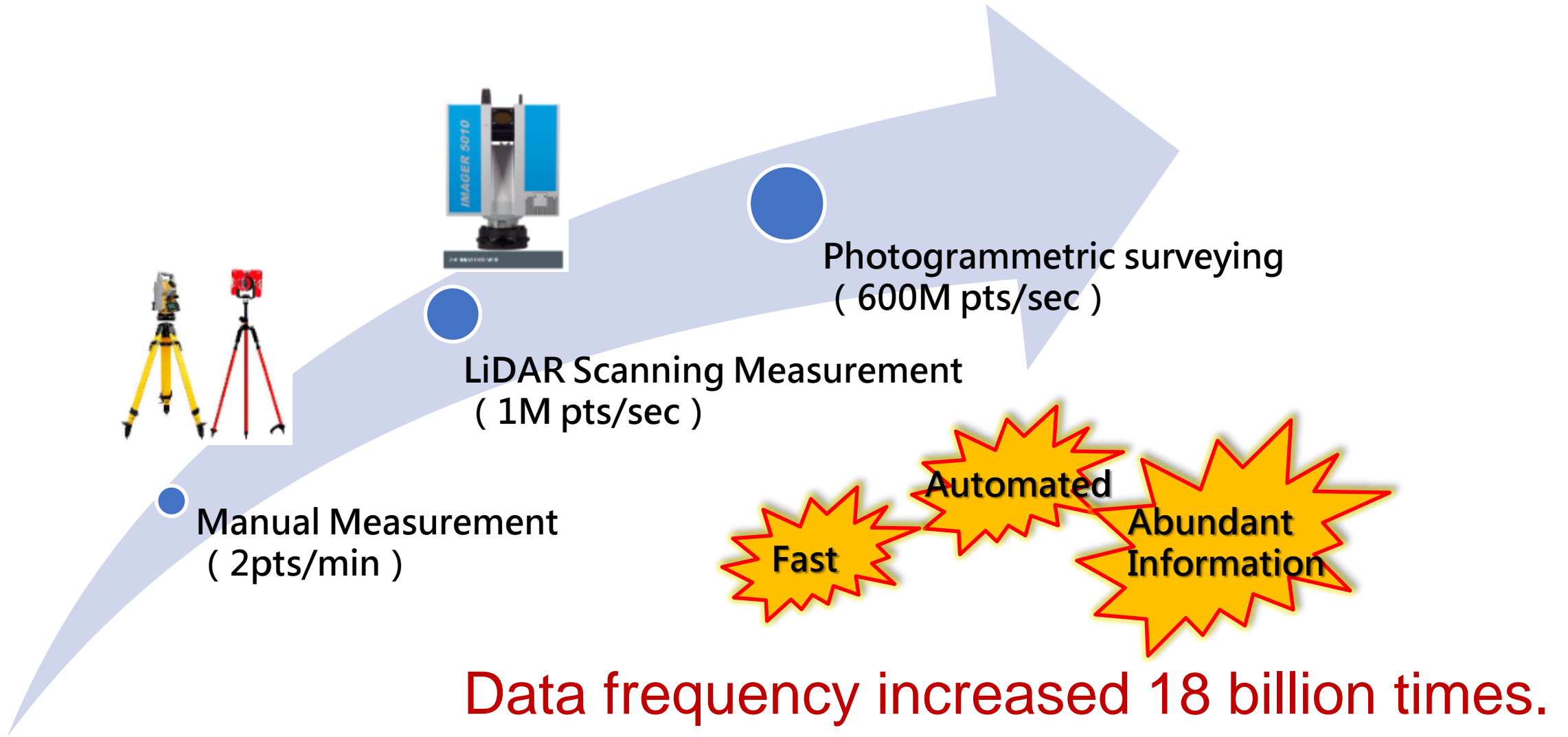
MMS: 1 million points per second (1MHz).



UAV: 30 images per second, each image contains 20 million pixels (600 MHz).



# 01 Evolution of Sensing Technology

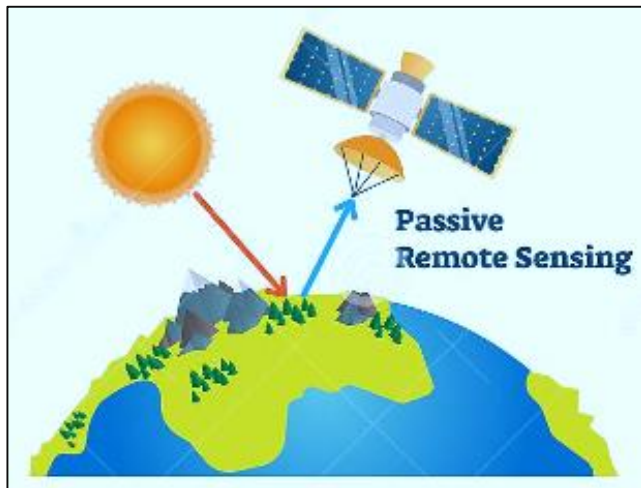




# 01 Evolution of Sensing Technology

## □ Remote sensing :

- Acquiring data from a far distance without touching the target.



### Passive

- Passive systems detect solar reflected radiation.
- EX : optical, multi-spectral, near-infrared, thermal



### Active

- Active systems emit signals (laser, radar, etc.) and record the returned ones.
- EX : LIDAR, RADAR or SAR



# 01 Evolution of Sensing Technology

- Passive systems  
optical, near-infrared



## Principle

Most objects have different reflection in the visible light band (400-700 nm) and near-infrared (800 nm - 2500 nm).

## Application

Combined with computer vision to identify target objects and the principle of spectral reflection to understand plant growth status

## Infrared



## Principle

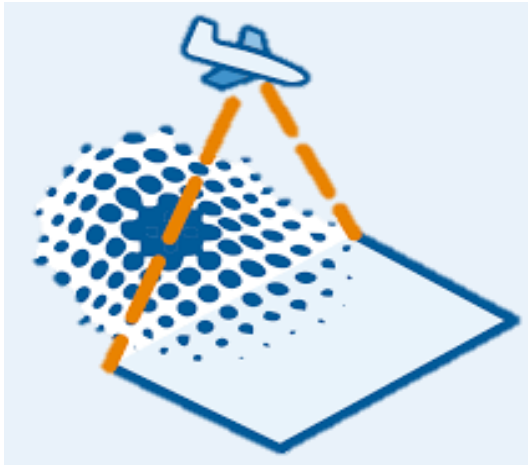
Infrared ray (750 nm-100  $\mu$ m), most of the thermal radiation emitted by objects at room temperature is in this band.

## Application

Solar panel inspection, air pollution monitoring

## □ Active systems

### LIDAR



#### Principle

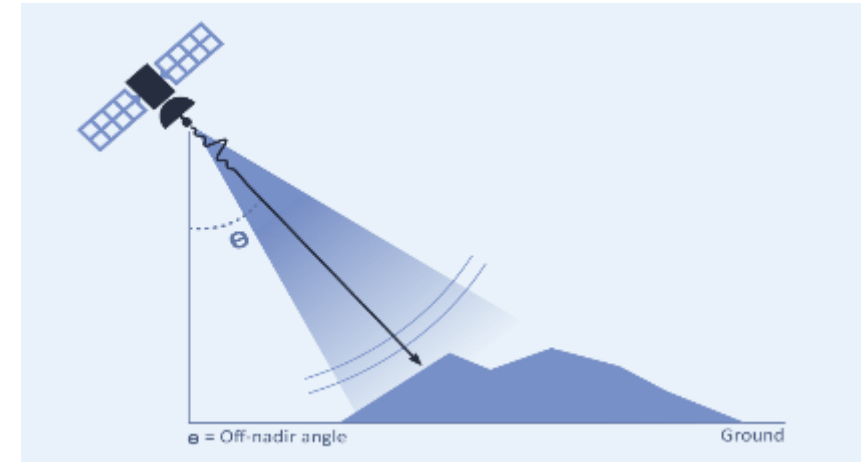
It uses light in the form of a pulsed laser to measure ranges.

#### Application

Producing DEM, iceberg monitoring, tree volume estimation.

### InSAR

(Interferometric Synthetic Aperture Radar)



#### Principle

It is a technique for mapping ground deformation using radar images of the earth's surface that are collected from orbiting satellites.

#### Application

Surface deformation, infrastructure monitoring, biomass estimation.

## □ Advantages and disadvantages

### Passive: Optical



SPOT

#### Advantages

Easy to identify and apply

#### Disadvantages

Affected by light and weather condition

### Active: Radar



Radarsat

#### Advantages

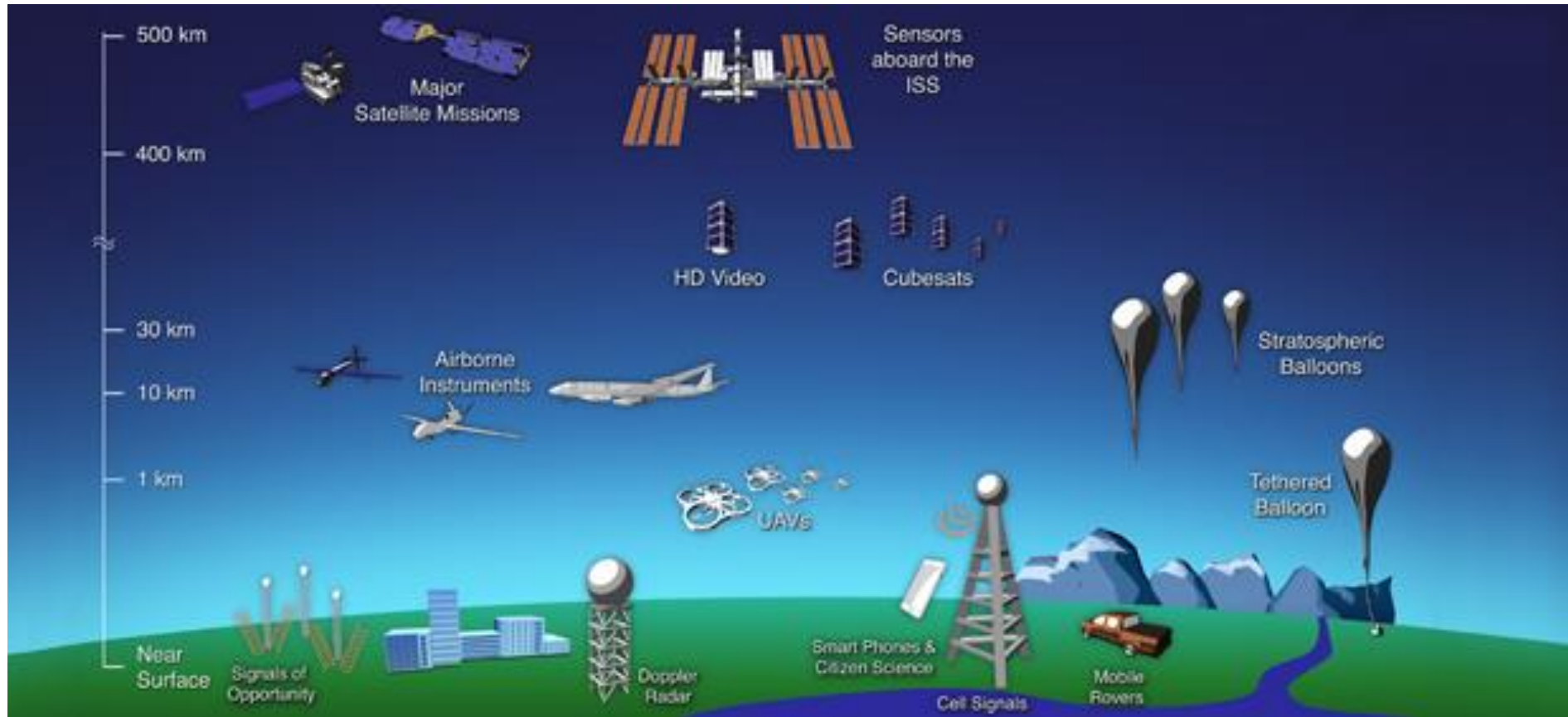
Not affected by weather and can even penetrate the surface of objects

#### Disadvantages

The process of raw data is much complicated

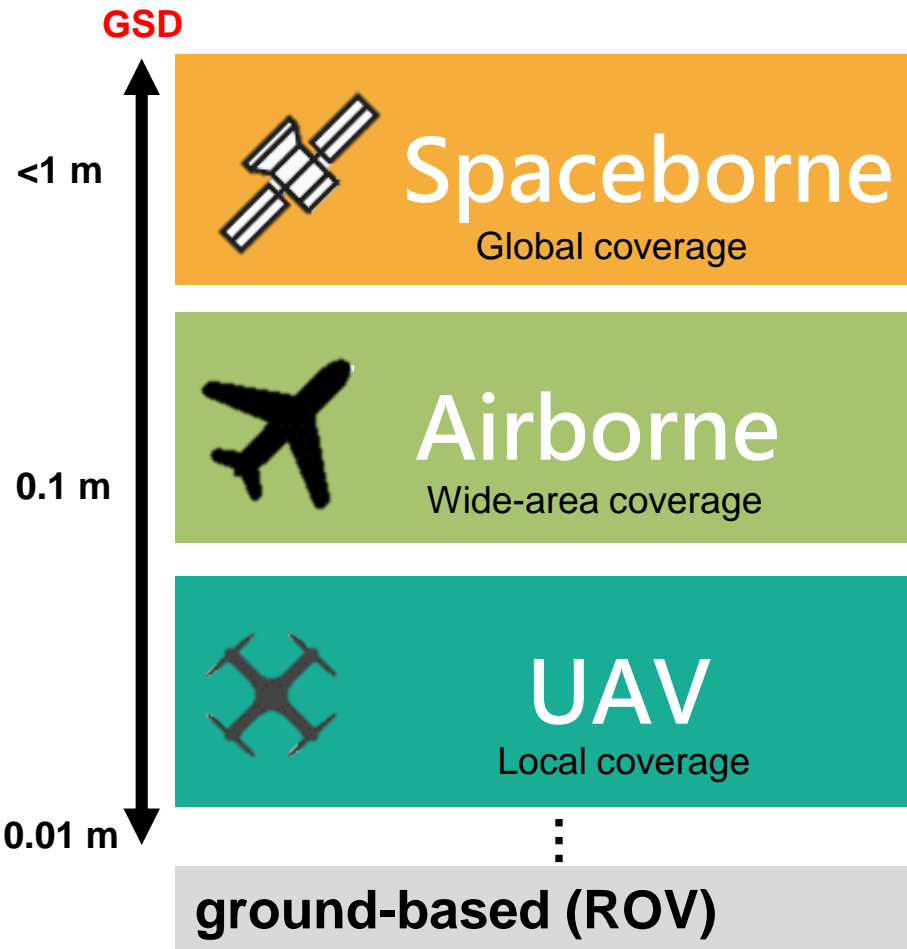
# 01 Evolution of Sensing Technology

- Different platforms :
  - satellite-borne, airborne, UAV-Borne, vehicle-mounted



# 01 Evolution of Sensing Technology

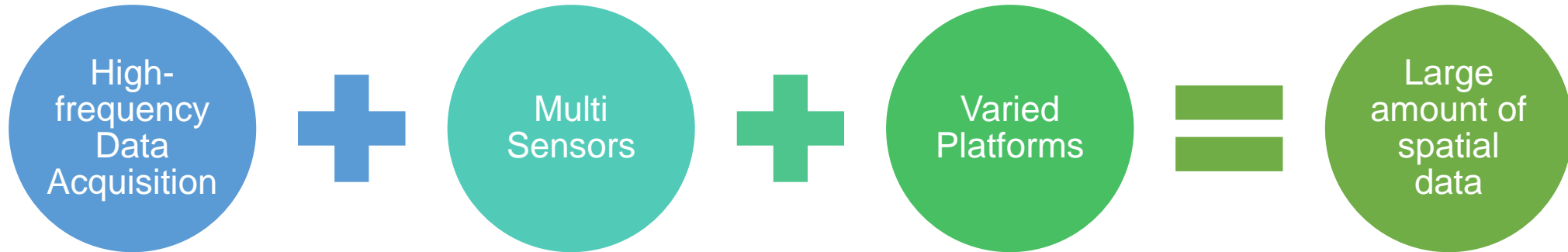
- RS sensors can be equipped on different platforms, including ground-based, airborne, and spaceborne.



- **Advantages** : Covering a large area, data collection is not affected by weather.
- **Disadvantages** : Limited by the orbit of the satellite.
- **Advantages** : High resolution, relatively high mobility, equipped with sensor as needed.
- **Disadvantages** : Covering a small area and covered by clouds.
- **Advantages** : Ultra-high resolution, high maneuverability (free flight path planning), and equipped with sensor as needed.
- **Disadvantages** : Covering a very limited area.



# 01 Evolution of Sensing Technology



Up to several MHz

Image, Laser, Radar, Multi-spectral

Ground, aerial, and space

**Huge information to be analyzed!**



# 02 Artificial Intelligence







# Task : Find Jen-Yu Han





# Task : Find Jen-Yu Han

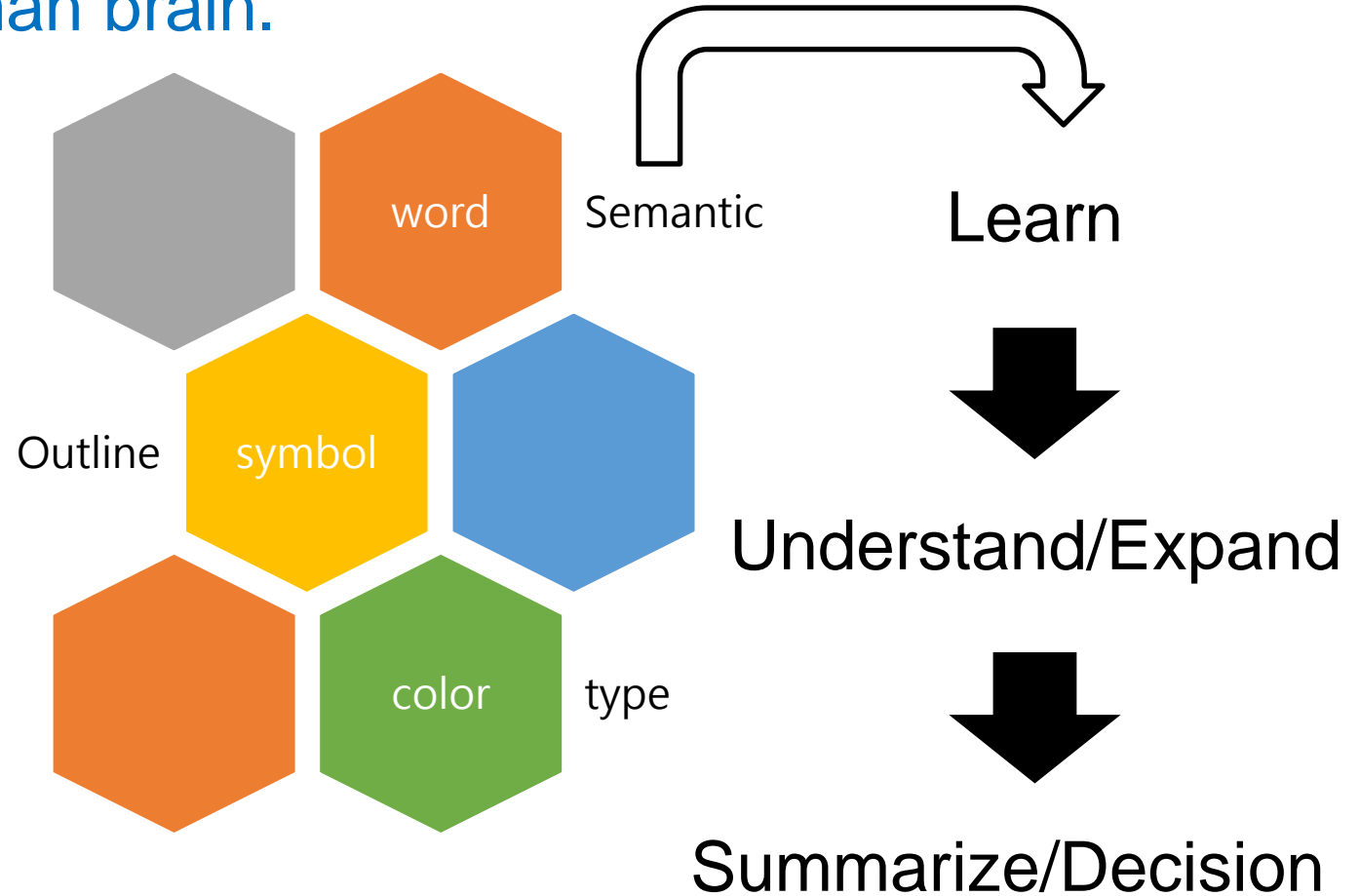
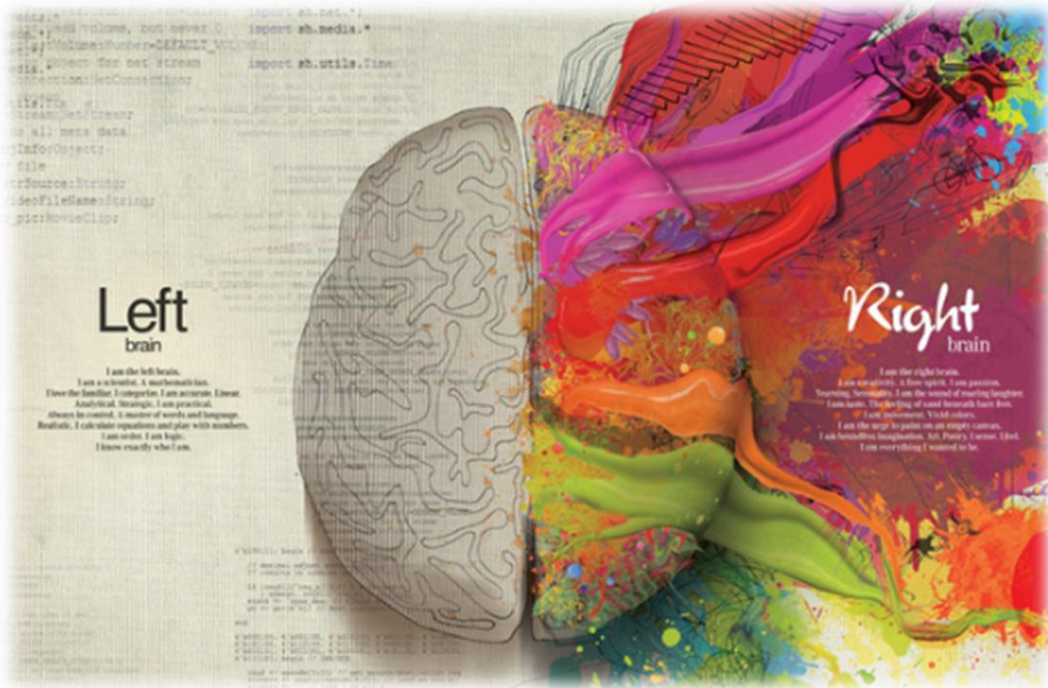




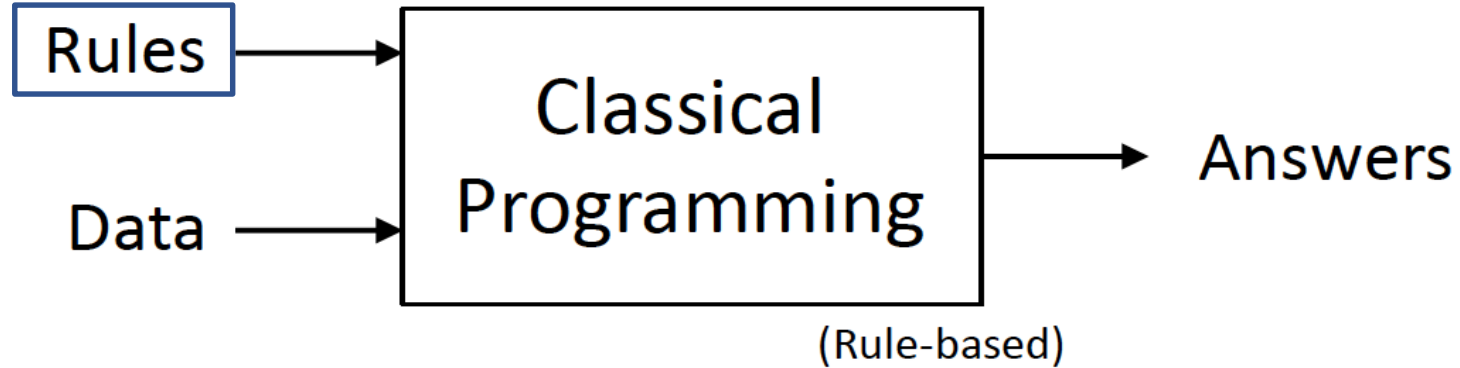
# Task : Find Jen-Yu Han



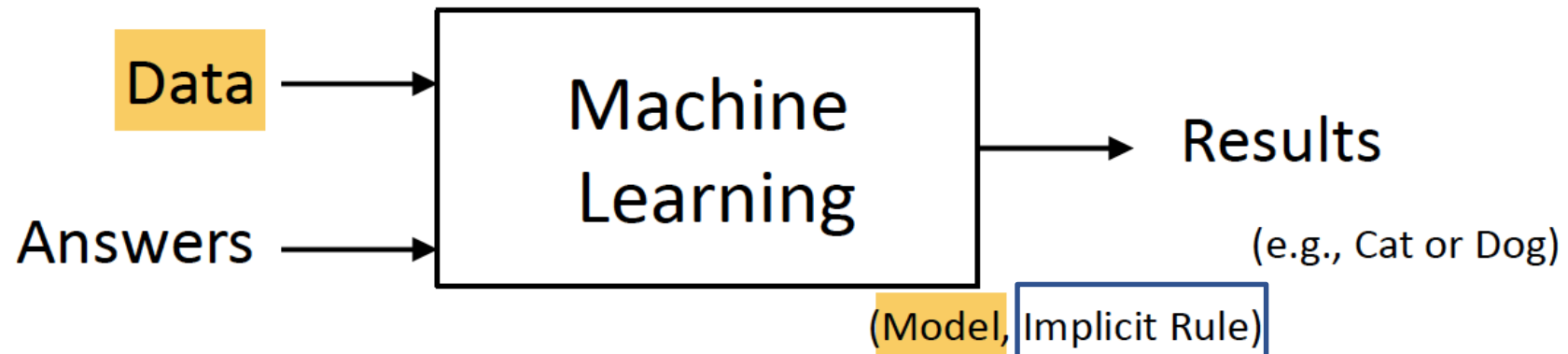
**Machine Learning** Let machines replace some of the functions of the human brain.



## Classical Programming vs ML



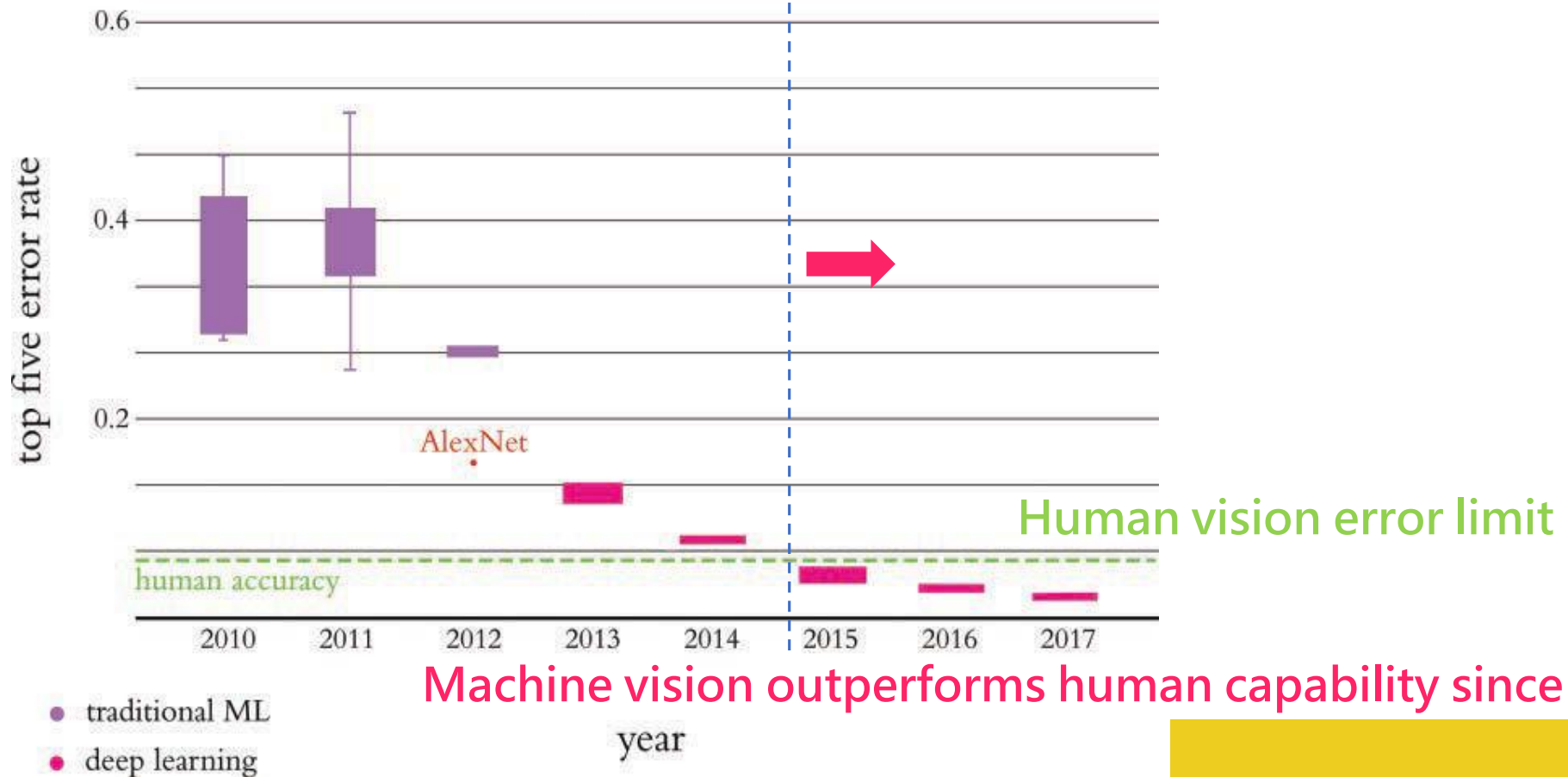
### Machine Learning



# 02 Introduction to AI

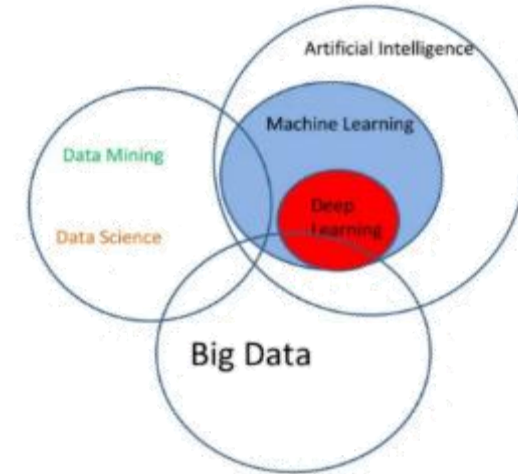
- Computer vision based on deep learning has already surpassed the limits of human eyesight.

ILSVRC (the ImageNet Large Scale Visual Recognition Challenge)

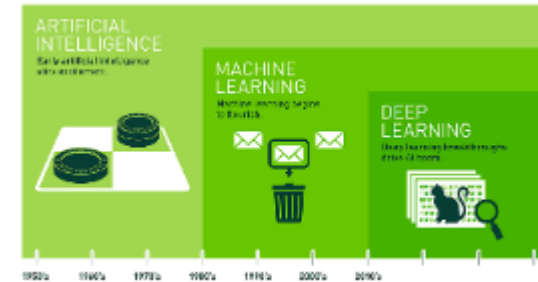


## □ Various terminologies concerning AI

	Machine Learning (ML)	Deep Learning (DL)	Ensemble Learning
Method	<ol style="list-style-type: none"> <li>Supervised Learning</li> <li>Unsupervised Learning</li> <li>Reinforcement Learning</li> </ol>	<ol style="list-style-type: none"> <li>CNN</li> <li>Regions with CNN (R-CNN)</li> <li>Faster RCNN</li> <li>Schematic Segmentation</li> <li>RNN</li> <li>LSTM</li> </ol>	<ol style="list-style-type: none"> <li>AdaBoost</li> <li>XGBoost</li> </ol>
Application	<ul style="list-style-type: none"> <li>Image and voice recognition</li> <li>Computer vision, medical diagnosis</li> <li>Prediction, classification,</li> </ul>	<ul style="list-style-type: none"> <li>Voice assistant</li> <li>Autonomous driving</li> <li>Data augmentation</li> <li>Image segmentation</li> <li>Recommendation and email response system</li> </ul>	

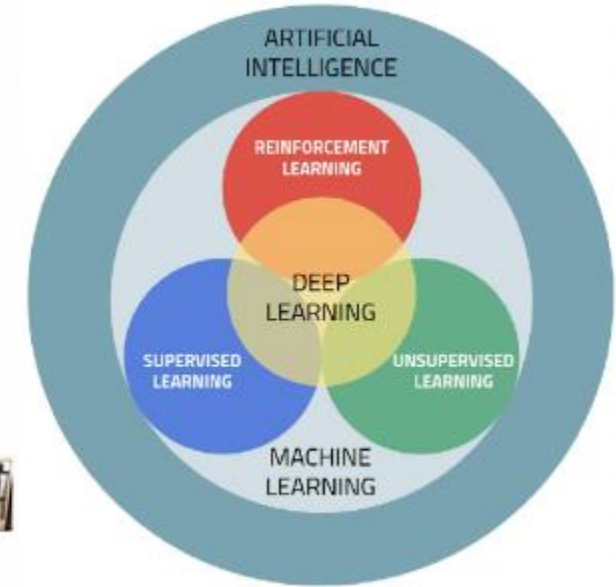
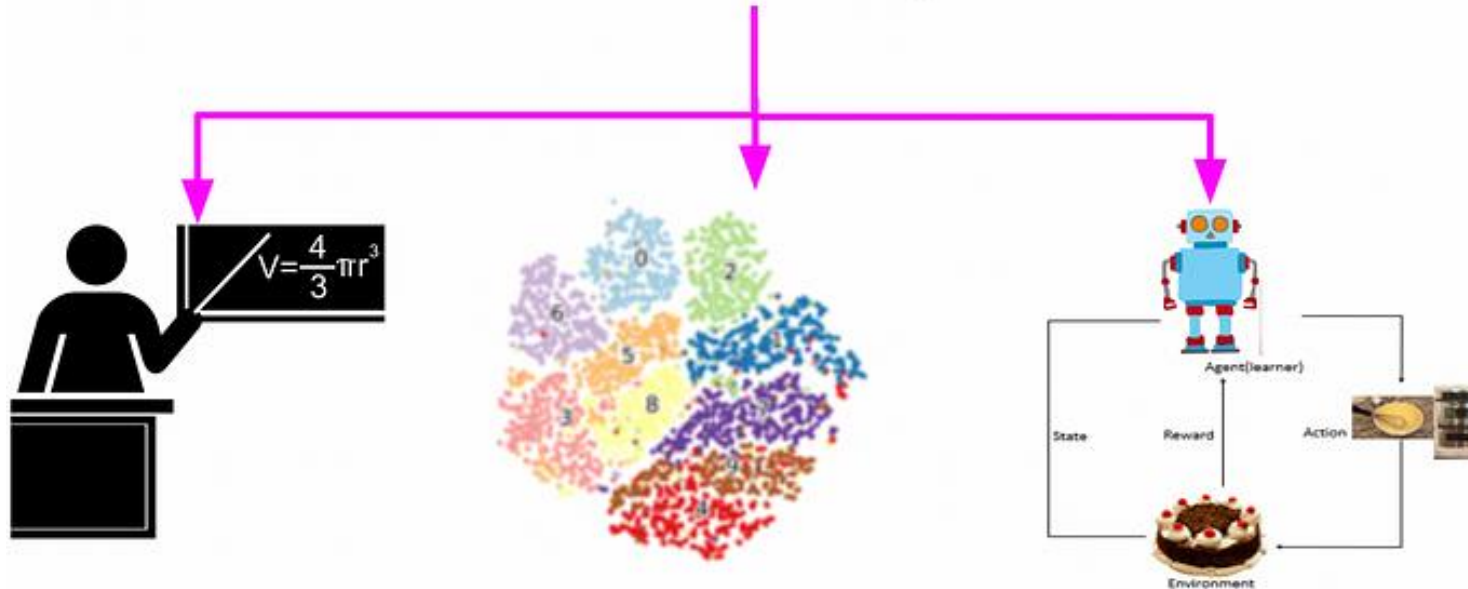


$$AI \geq ML \geq DP$$



ref : nVIDIA

## Machine Learning



### Supervised Learning

Dataset features need to be labeled

Linear Regression · Naive Bayes · Decision Tree...

### Unsupervised Learning

No labels, no predictions

k-means · DBSCAN · dimension reduction...

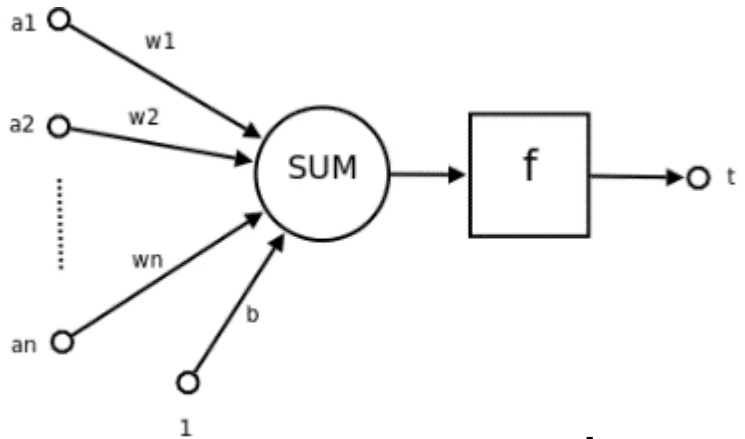
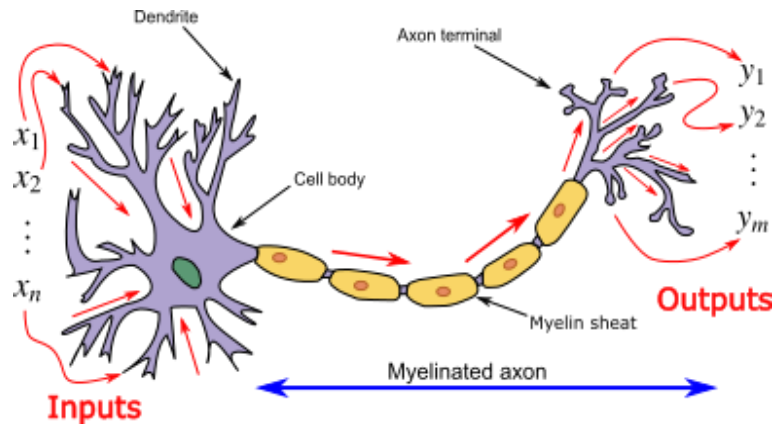
### Reinforcement Learning

Need feedback, not direct labels

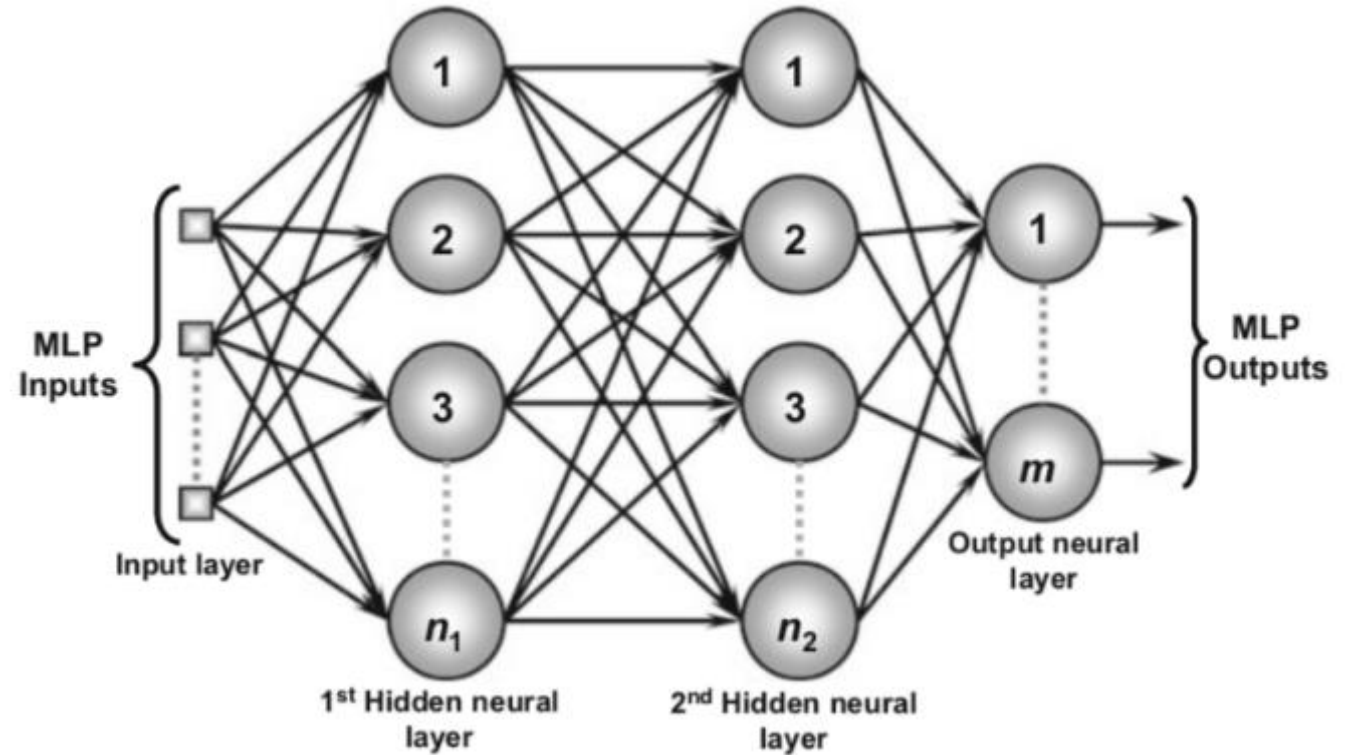
Google AlphaGo (2016)



## □ Introduction to Neural Networks



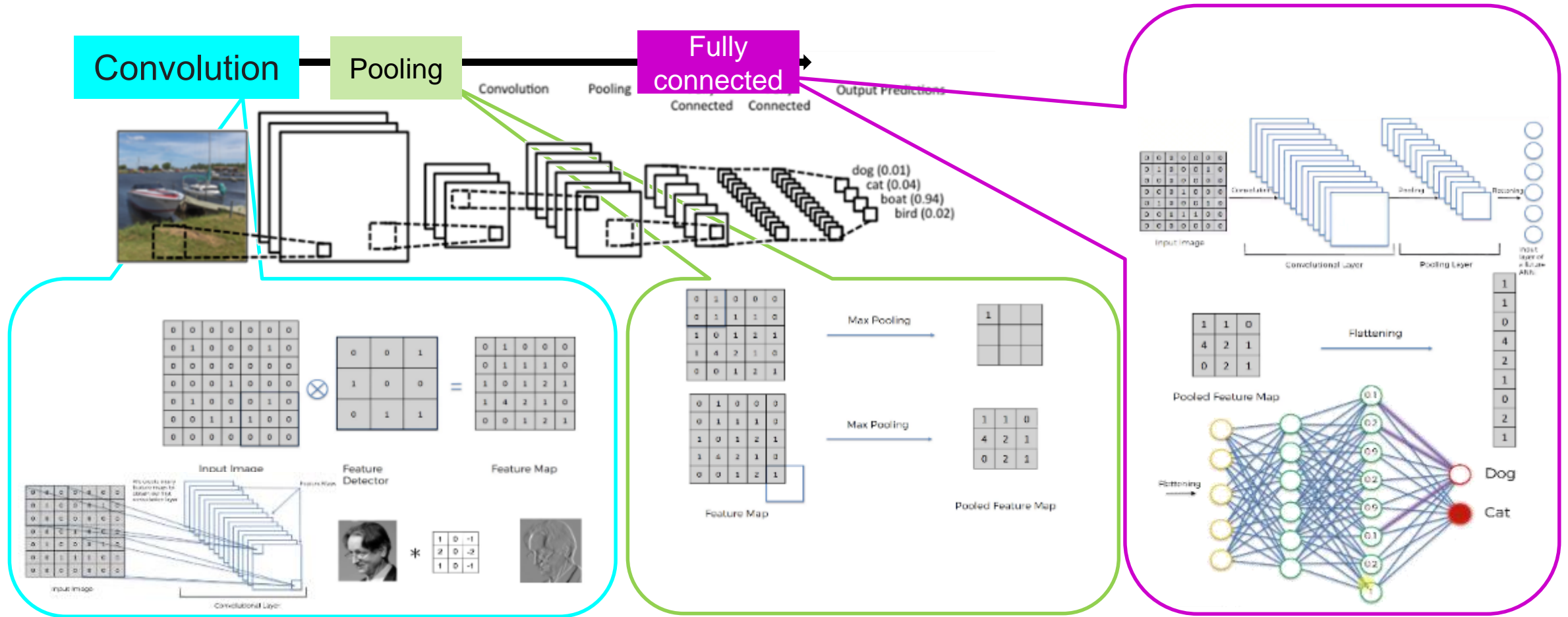
A perceptron network



A multilayer perceptron network

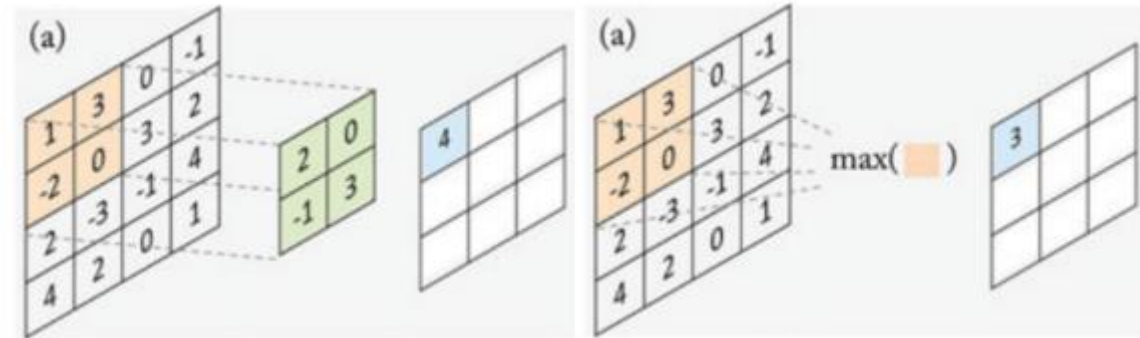
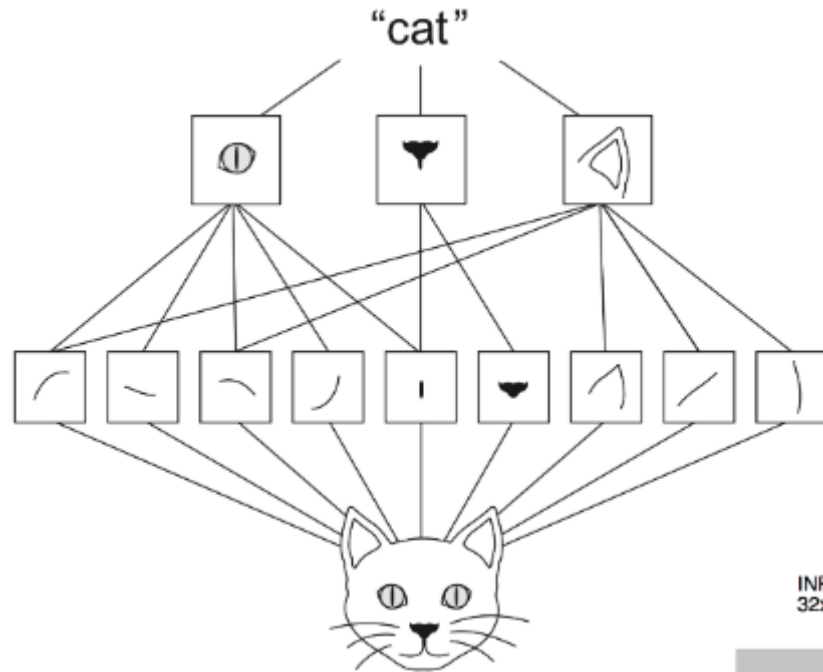
# 02 Deep Learning

## □ Deep Learning : Convolutional Neural Network (CNN)



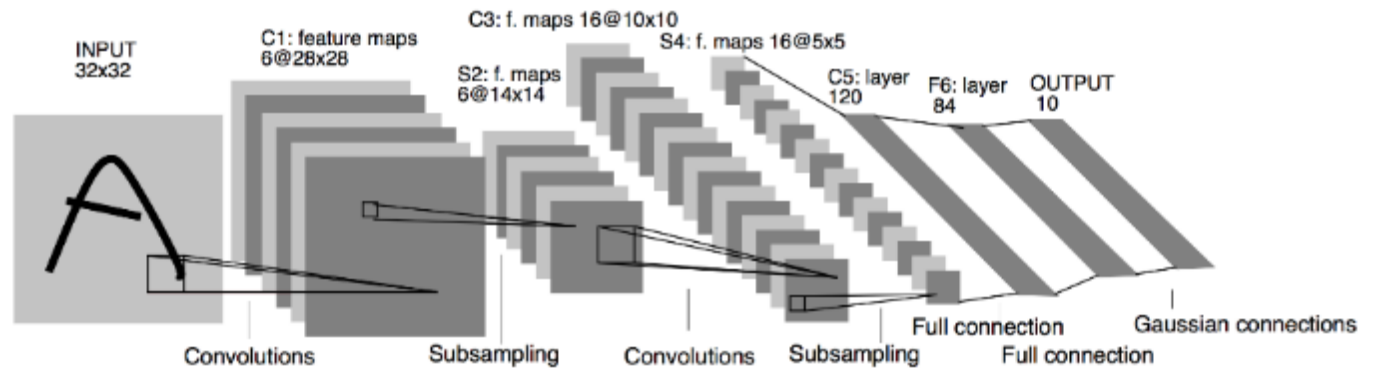
# 02 Deep Learning

## □ Deep Learning : Convolutional Neural Network (CNN)



Convolution operation

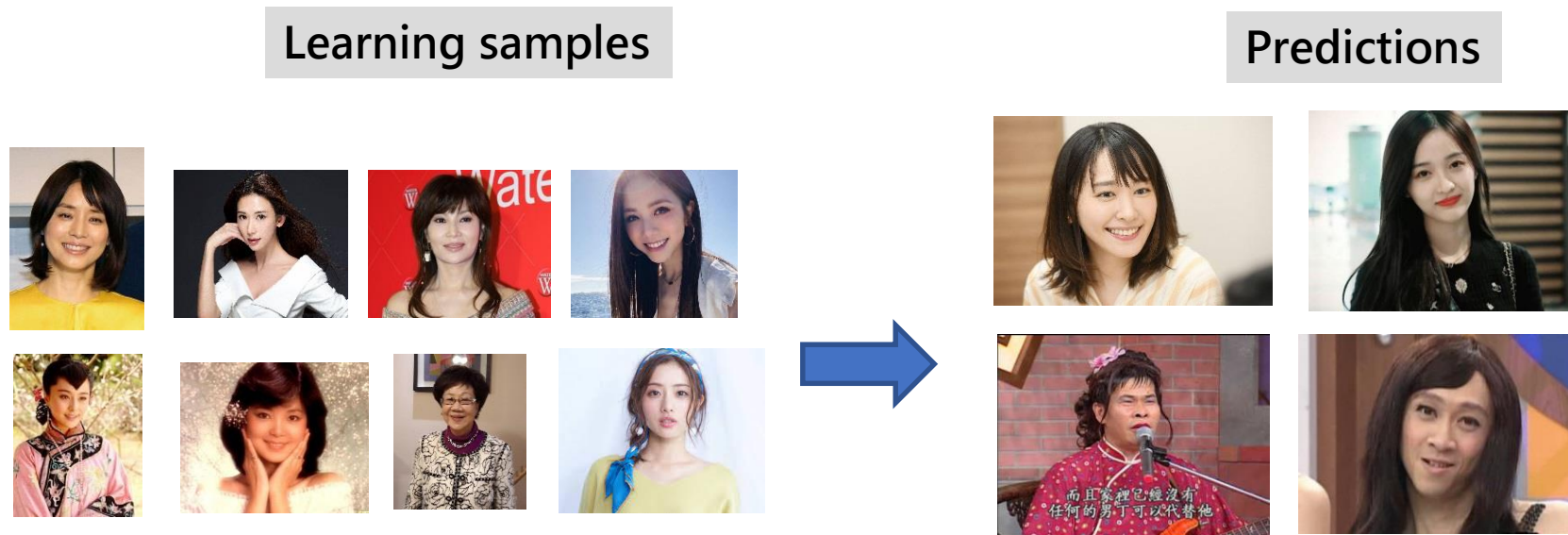
Subsampling operation



## □ Machine Learning vs. Deep Learning

Single neural layer ( ML ) : uses simple (explicit) features for learning.

Multi-layer neural network ( DL ) : uses multi-layer (implicit) features for learning.

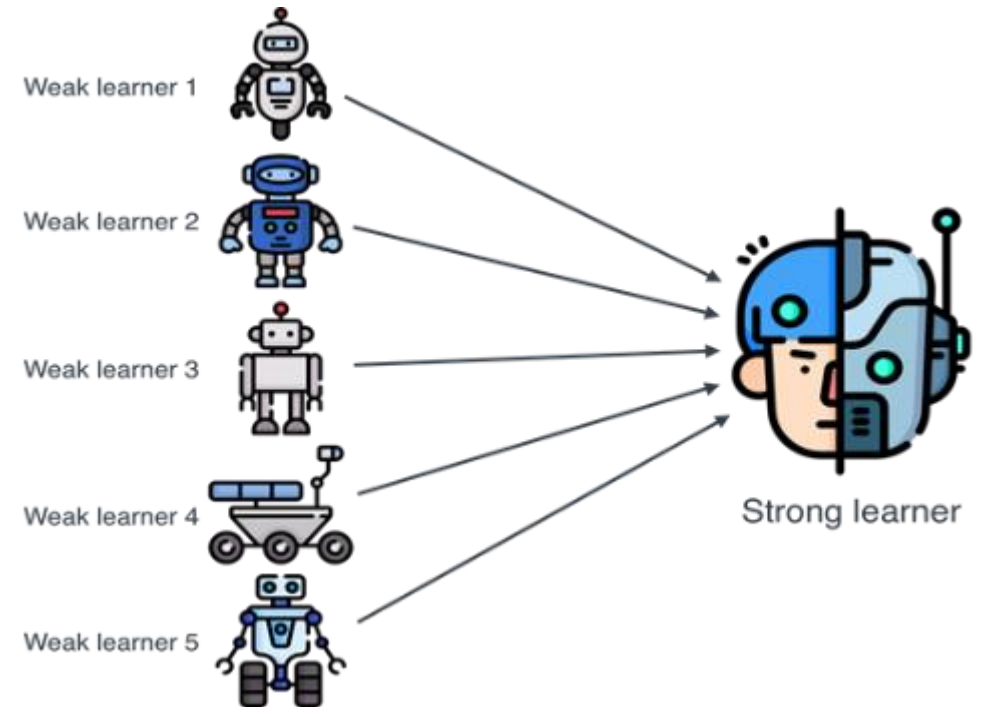
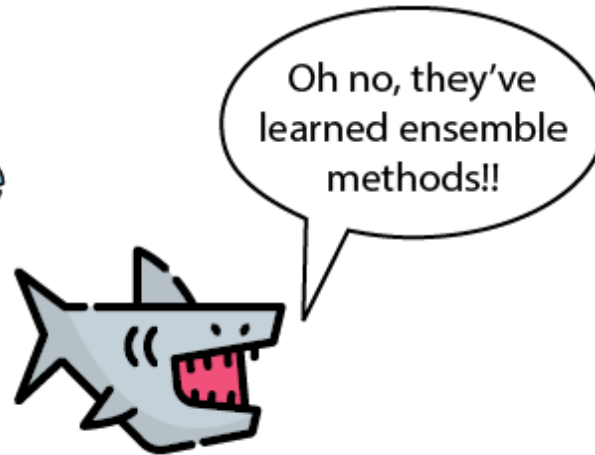
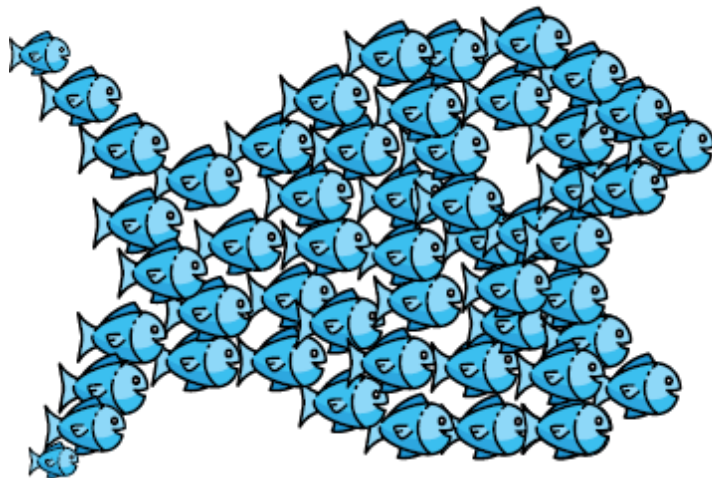


Mimics human's perception (intelligence)

# 02 Ensemble Learning

## □ Ensemble Learning :

In statistics and machine learning, ensemble methods use **multiple learning algorithms** to obtain better predictive performance than could be obtained from any of the constituent learning algorithms alone.





# 03 Application Cases

- UAV Application
- SAR Application



# UAV Applications for Intelligent river analysis

01

3D modeling from UAV  
images

02

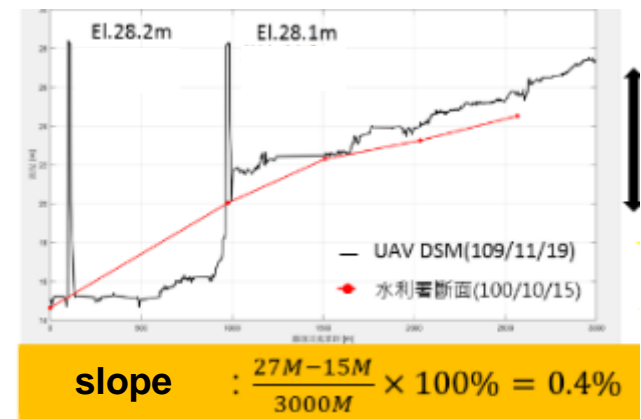
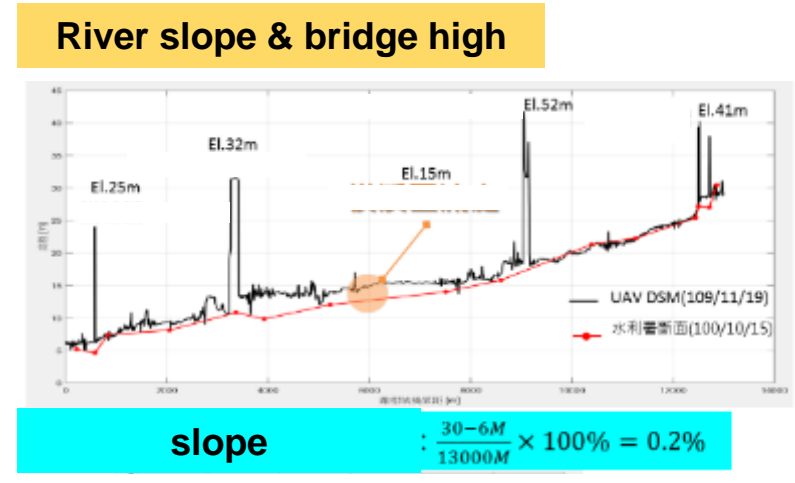
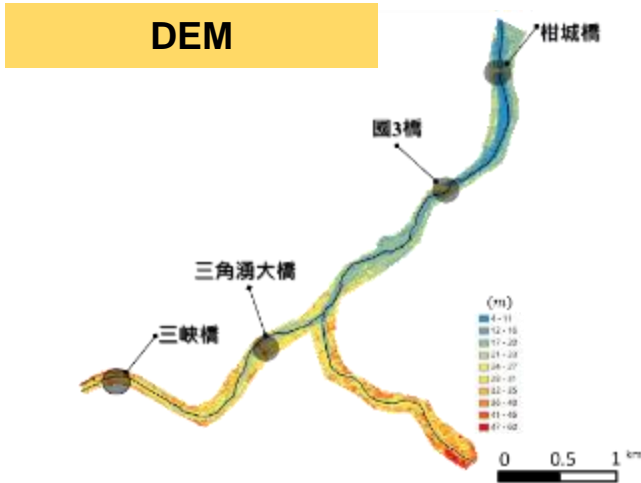
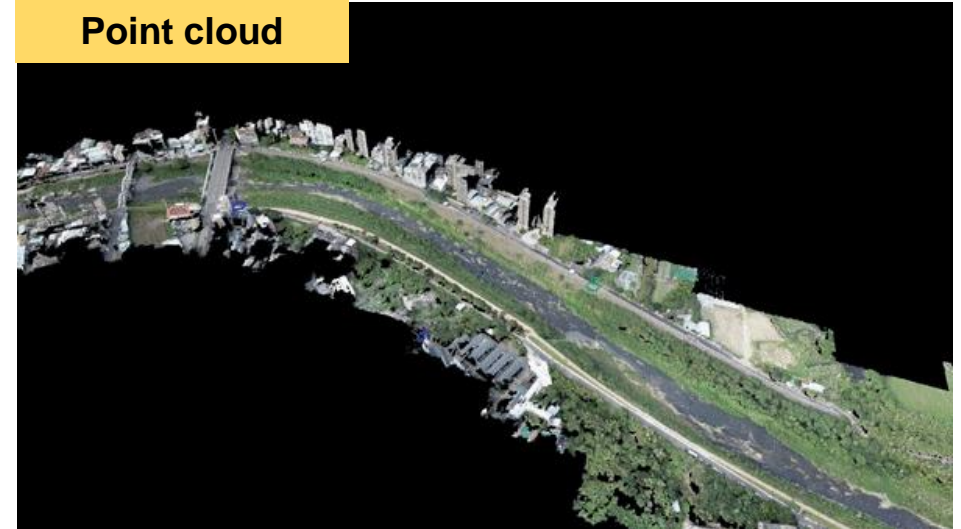
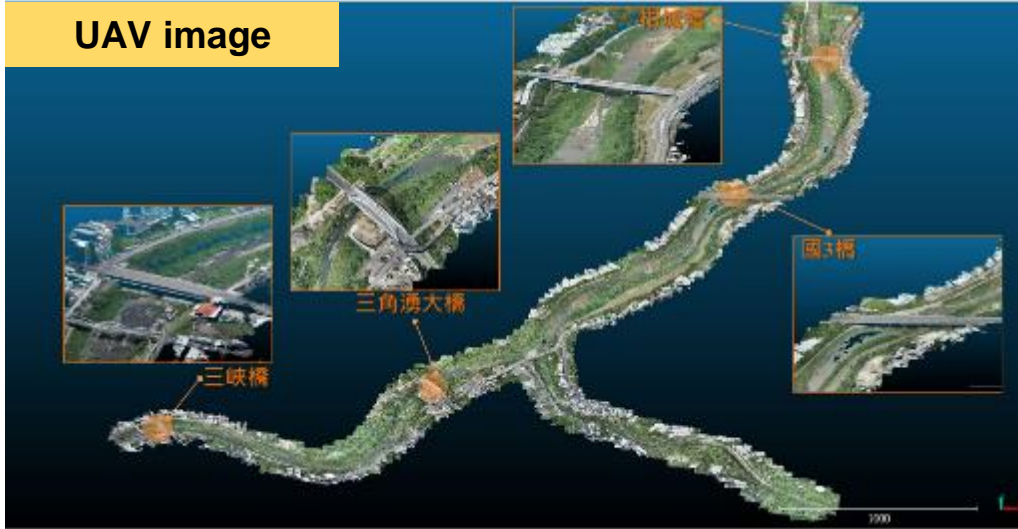
River hydraulic  
analysis

03

Flood simulation  
and early warning

# 03 Intelligent river analysis

□ 3D modeling from UAV images.





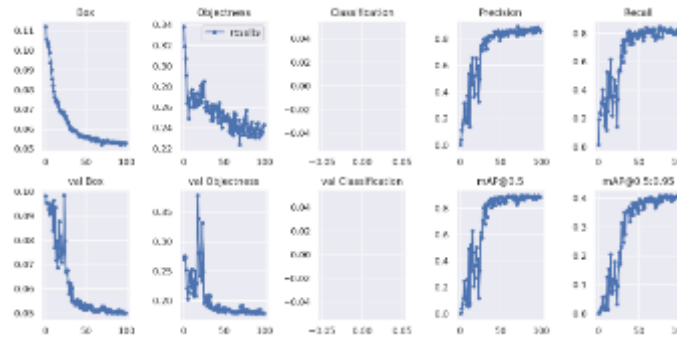
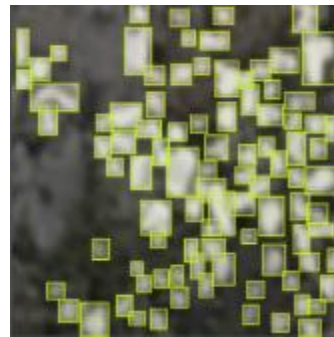
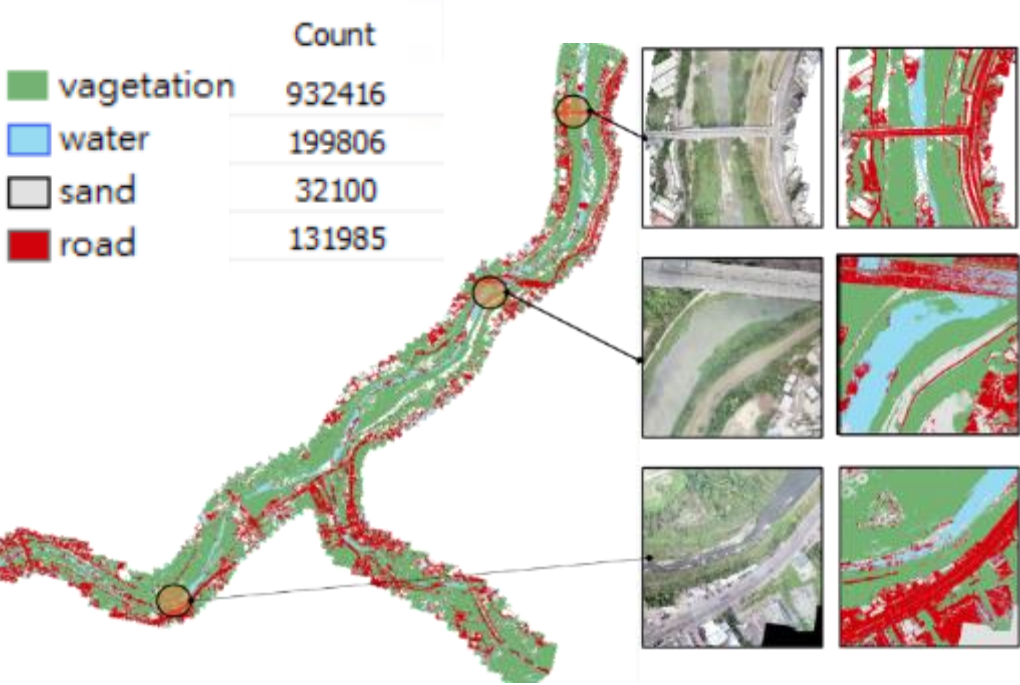
# 03 Intelligent river analysis

□ Intelligent analysis techniques for UAV image.

Image detection



Size analysis



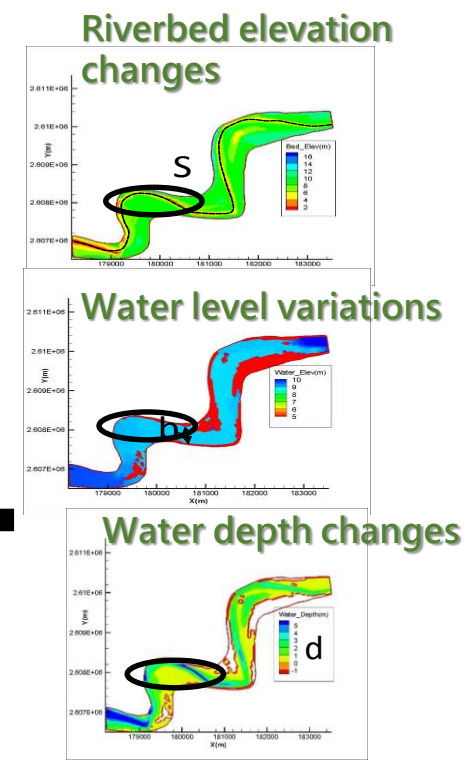
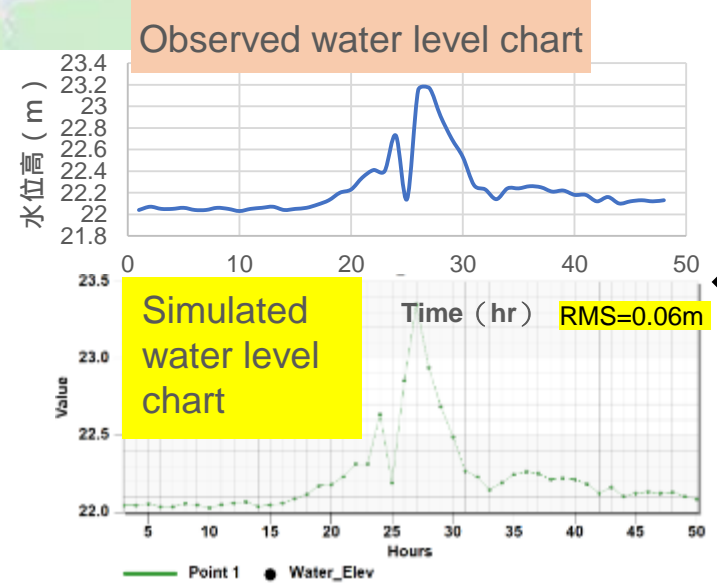
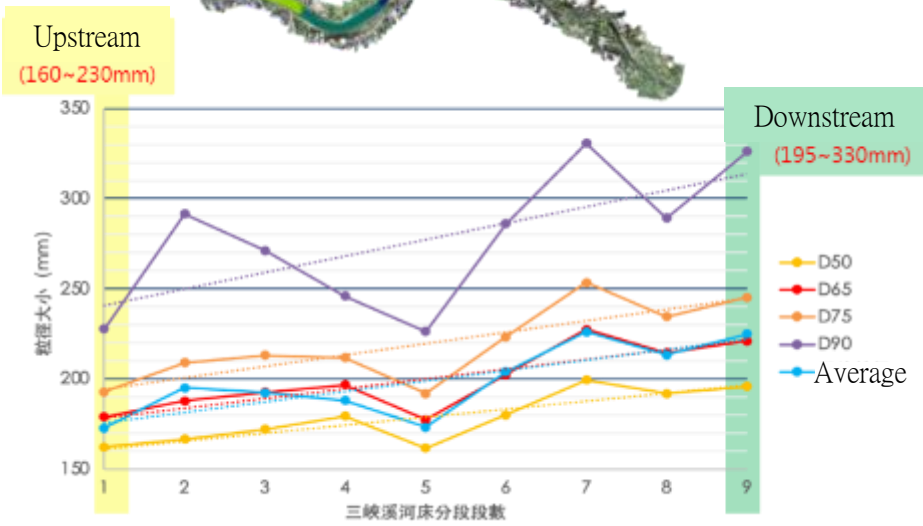
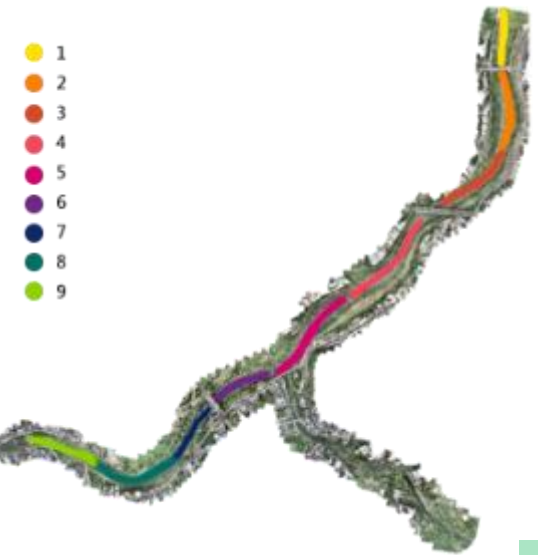
YOLOv5 training result



Visualization of riverbed grain size dimensions

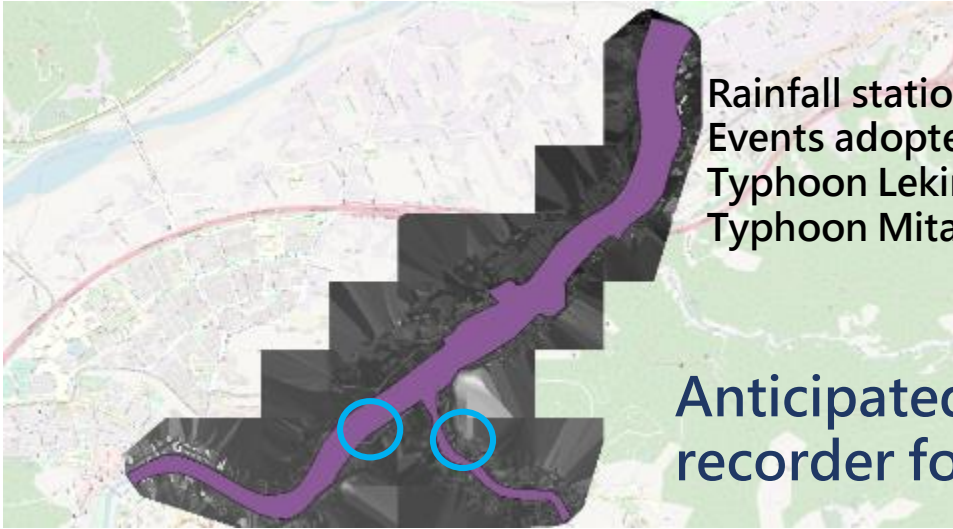
# 03 Intelligent river analysis

- Hydrological and hydraulic simulation: Calculating the Manning's n value, so that hydrological and hydraulic analyses can be achieved.



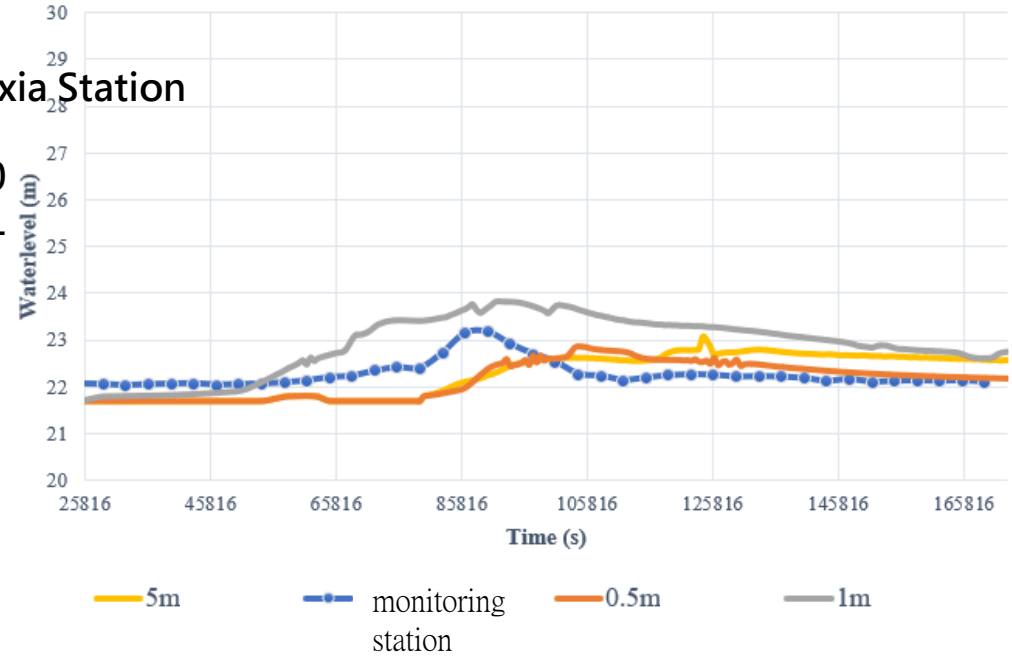
# 03 Intelligent river analysis

## □ Flood simulation and early warning



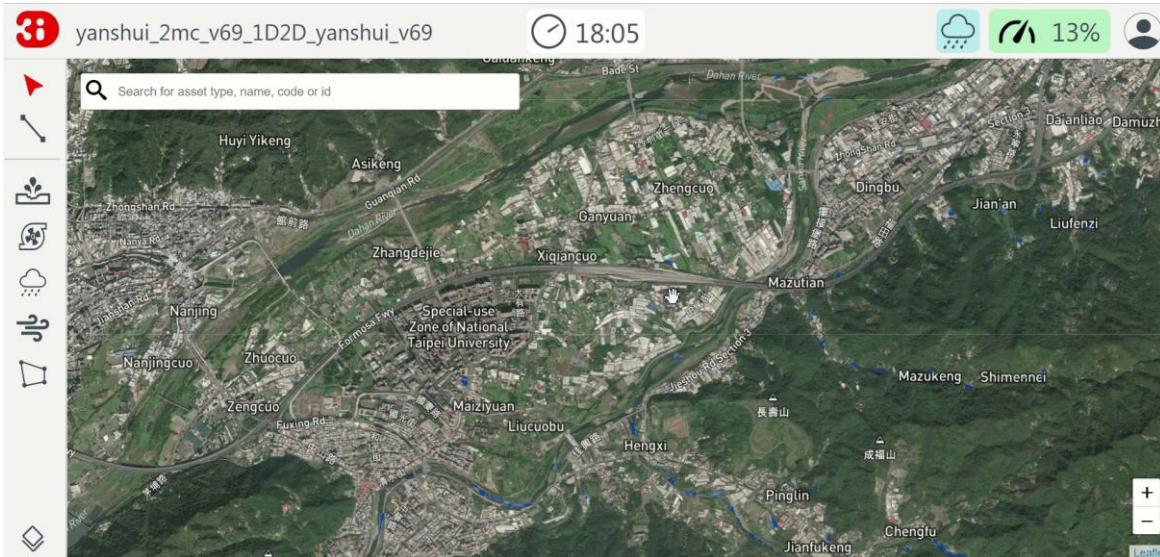
Rainfall station utilizes data from Sanxia Station  
 Events adopted:  
 Typhoon Lekima on 2019/08/08-8/10  
 Typhoon Mitag on 2019/09/30-10/01

Anticipated water level recorder for verification



### Errors for estimating water level

0.5m	1.66%
1m	3.26%
5m	2.15%
20m	15.32%



# UAV Application for Land development project

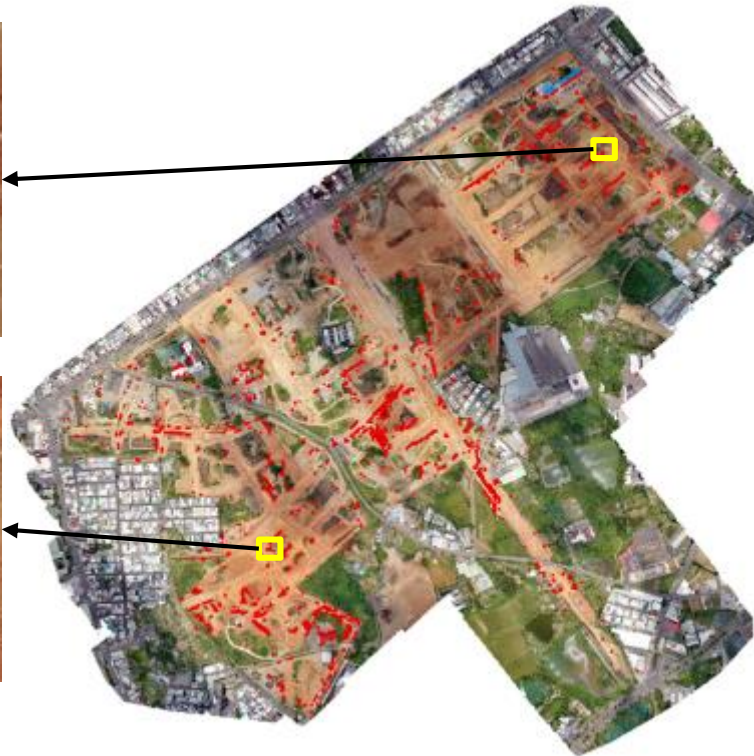
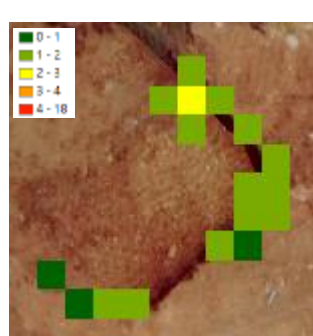


1. SVM : Create land cover change maps.
2. Yolo-v7 : Object detection, detecting target objects.
3. U-net : Semantic segmentation, category every pixel in an image.

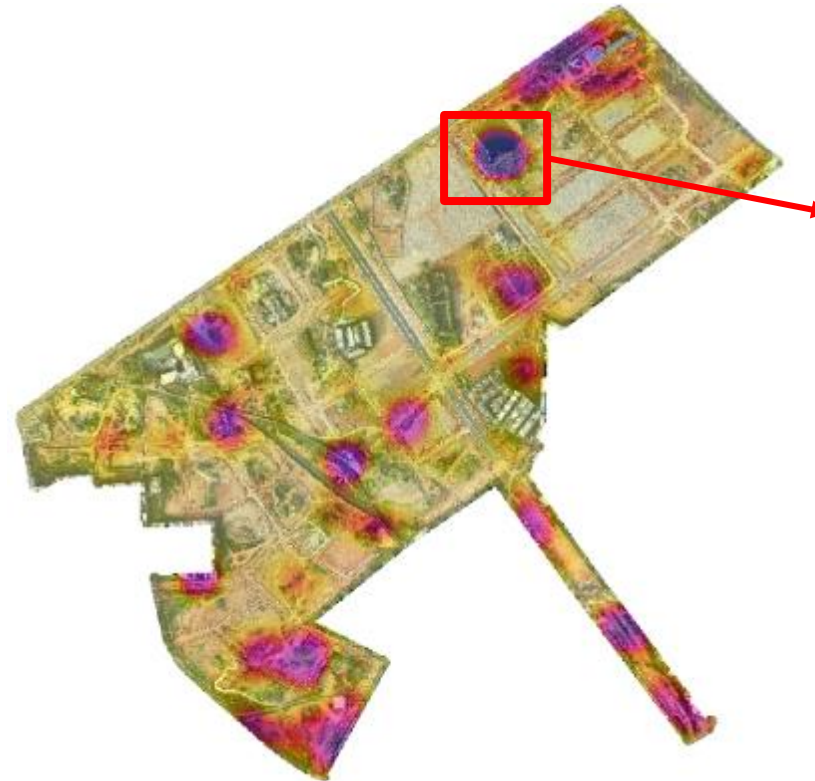
# 03 UAV for land development project

## Case 1 : Geomorphological Analysis for Large Height Difference Detection.

- This method enables the automated identification of regions with considerable elevation discrepancies and potential safety hazards (orthomap + DSM).



Large Height Difference Detection Map



Potential location of elevation difference



## Case 2 : Object Detection for Sewer Manhole and Shared Pipe.

- Using ortho-images and the object detection algorithm - Yolov7, detect the manhole construction locations.
- By integrating the design maps of the construction area, verify if there are any discrepancies in the positions of the constructed facilities.



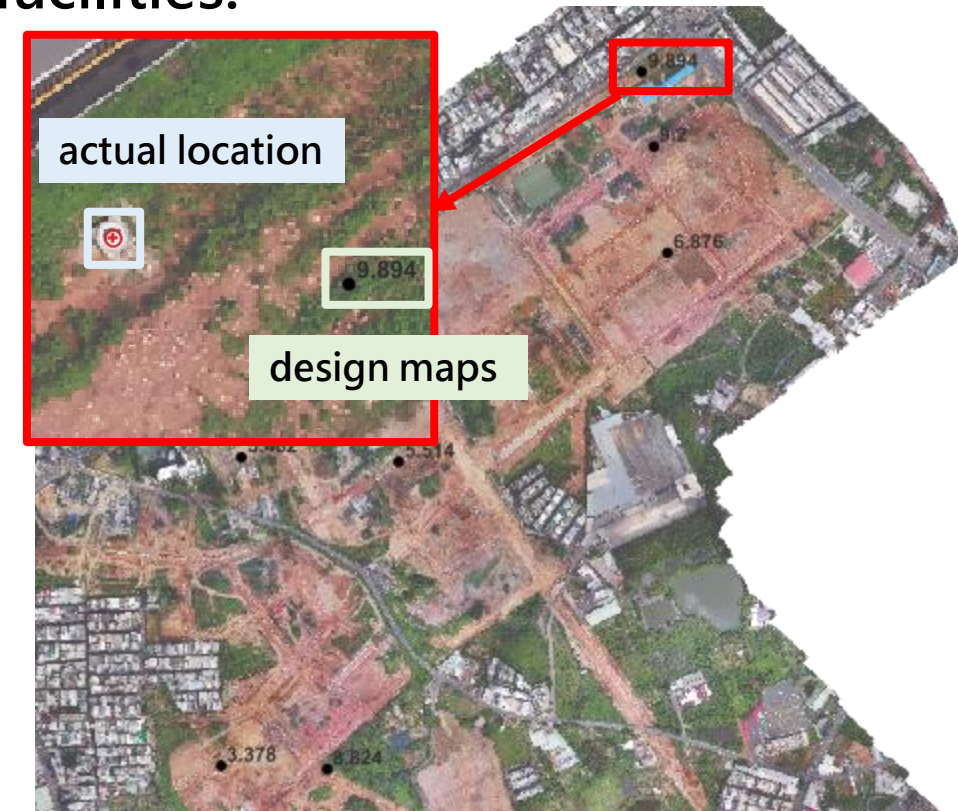
Shared pipe



Sewer manhole

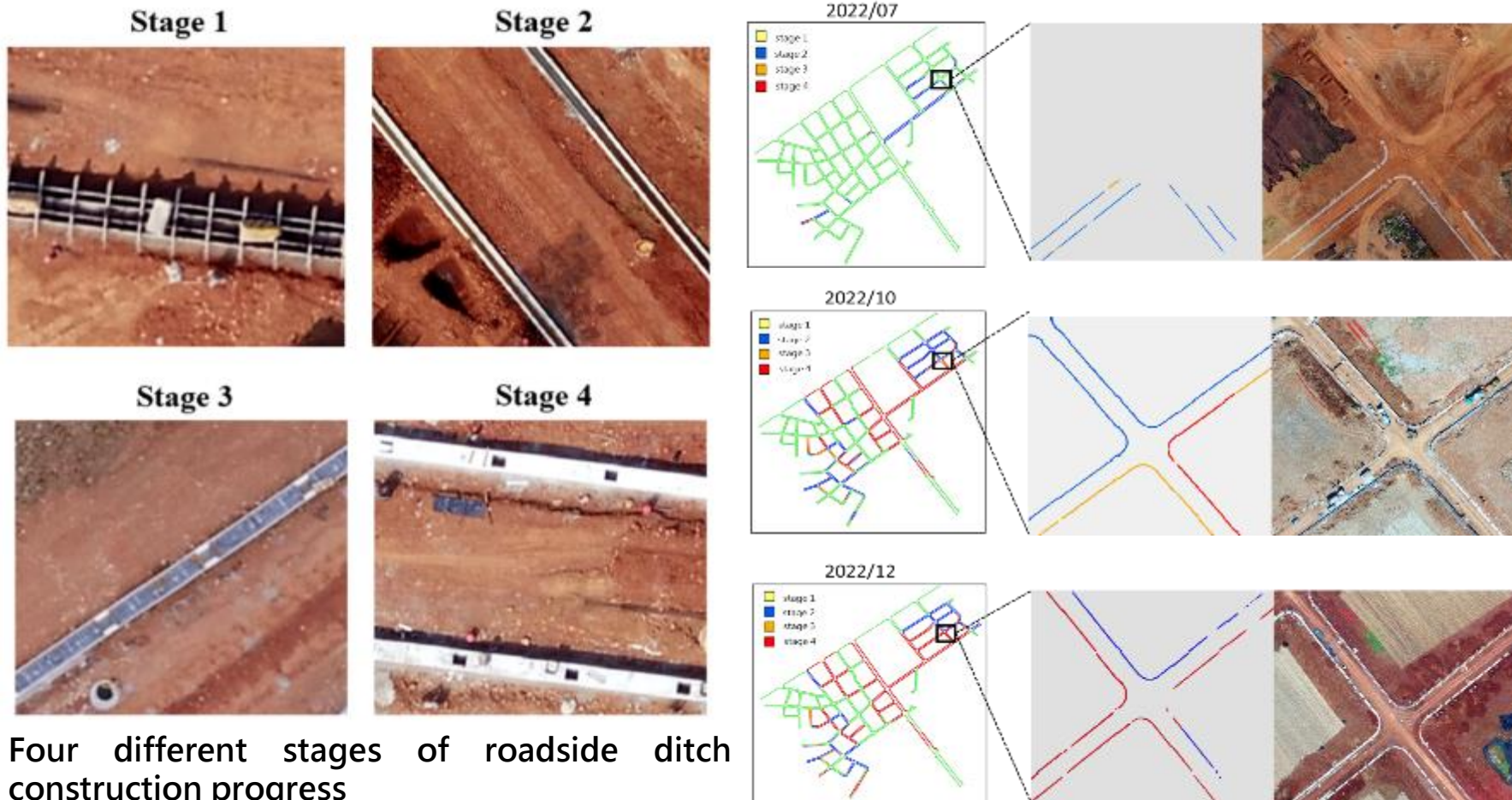
Model accuracy assessment

	Precision	Recall	F1	mAP@0.5
Sewer manhole	0.91	0.83	0.87	0.89
Shared pipe	0.85	0.81	0.83	0.90



## Case 3 : Image Segmentation for Roadside Ditch.

- Using multi-period UAV images, U-net can automatically detect the different construction progress of roadside ditches.

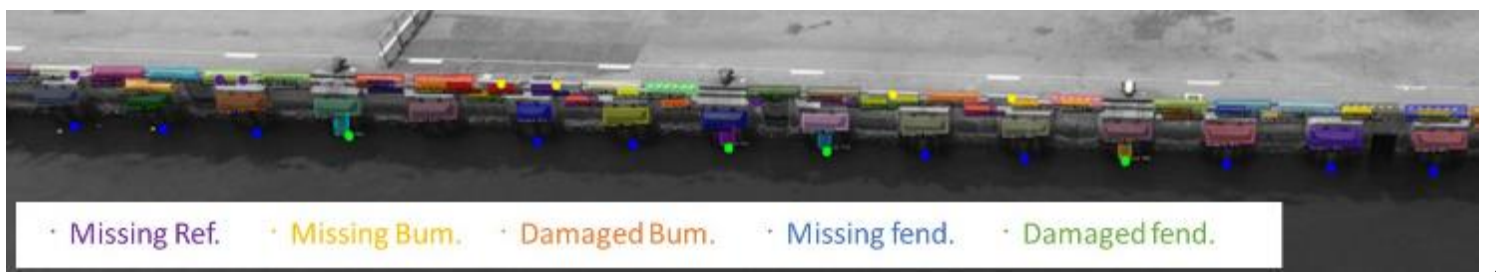
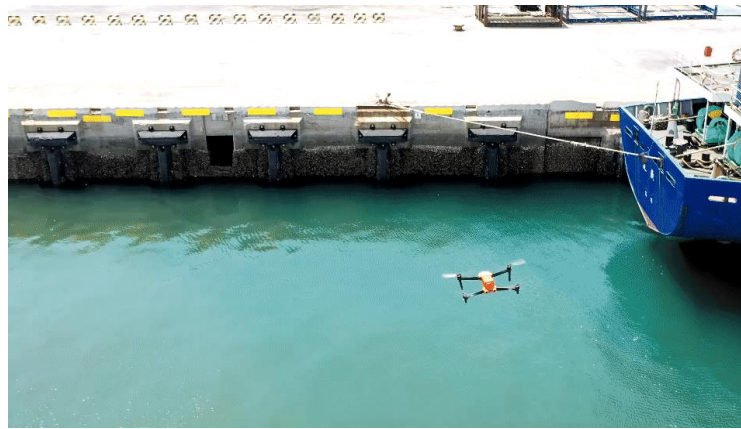
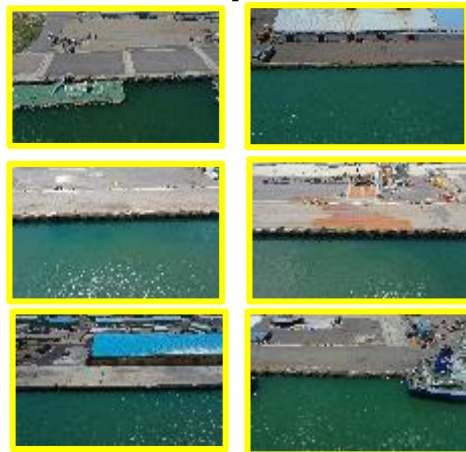


Four different stages of roadside ditch construction progress

Construction progress statistics for roadside ditch

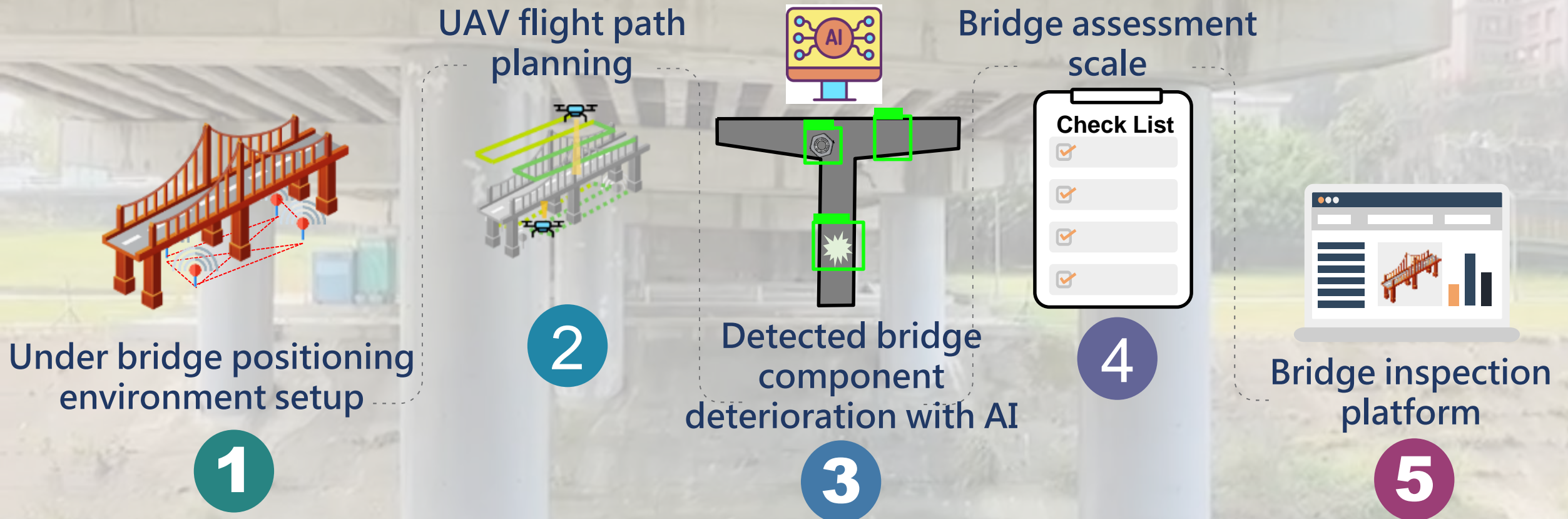
# 03 UAV for Port facility inspection

- Use UAV images to automatically detect the damaged (missing) facilities.



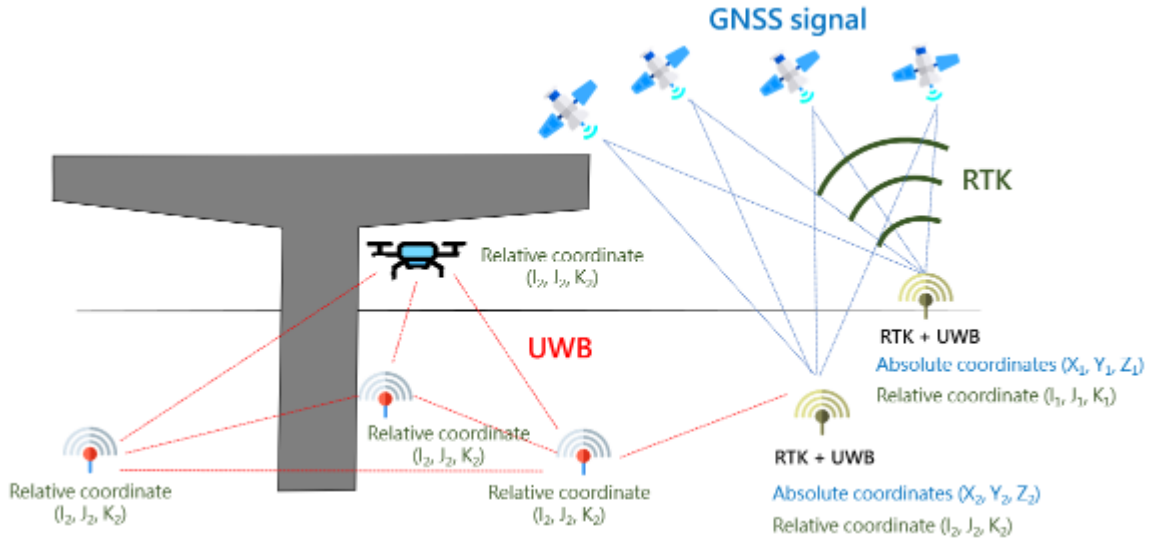


# UAV Application for Smart bridge inspection

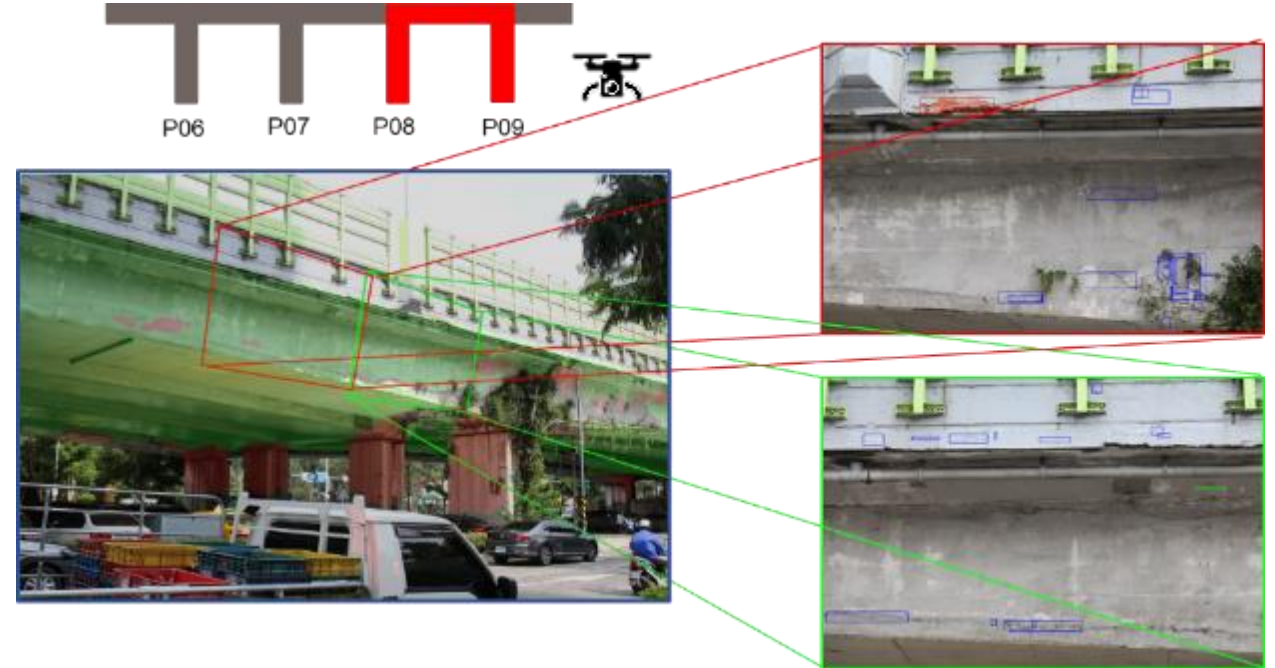


# 03 Smart port inspection

## Mobile Sensing



## Smart Inspection



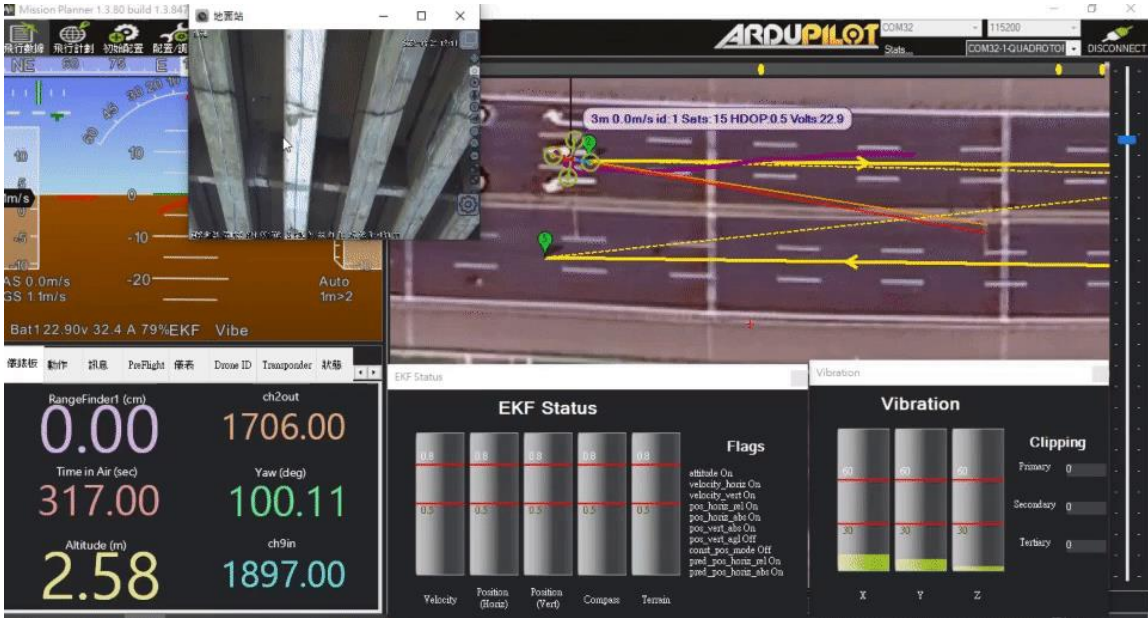
**Exposed  
reinforcing  
steel**

**crack**



# 03 Smart port inspection

□ Field inspection of in-service bridge :



□ UAV image :



# 03 Smart port inspection

- Detected bridge component deterioration with AI.

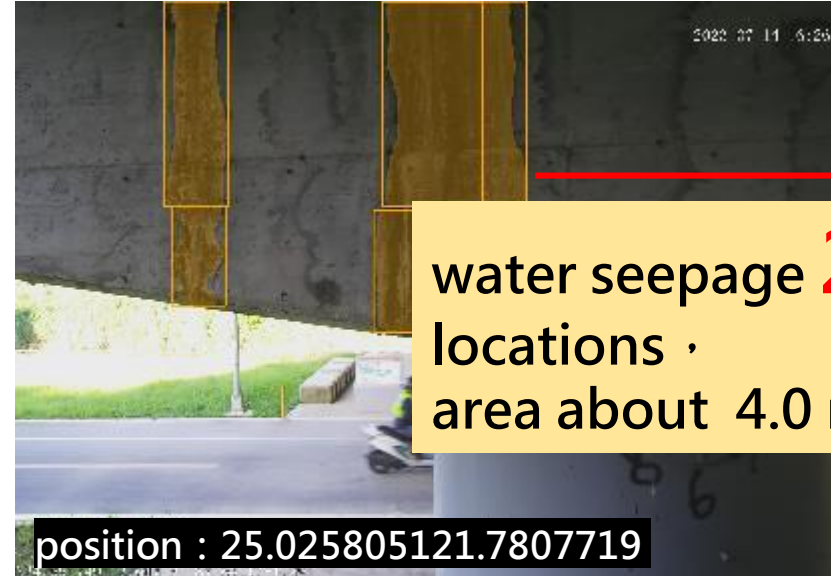
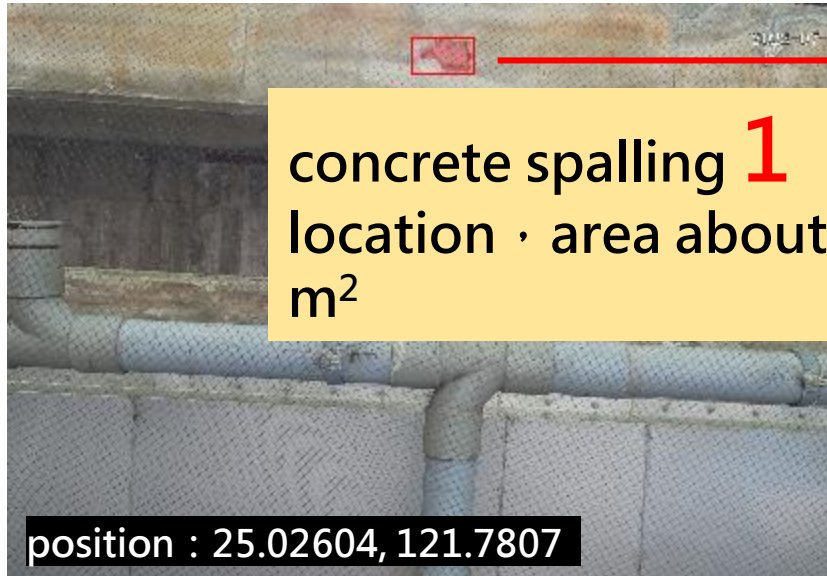


# 03 Smart port inspection

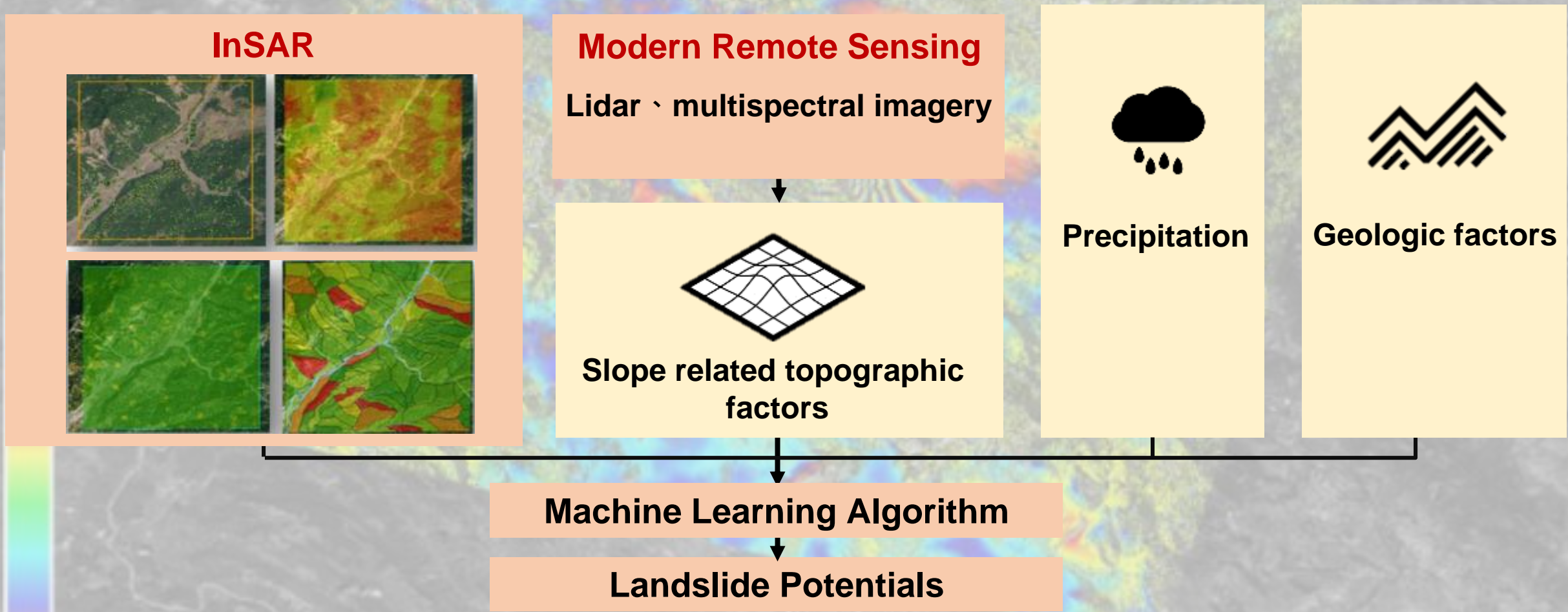
## Connected detection results to bridge assessment scale– DER & U。

檢測項目	位置	編號	D	E	R	U	損壞位置	劣化類型	
主梁			1	1	1	1	1G1	concrete spalling	
建議維修工法							數量	單位	單價
混凝土修復							1	處	

檢測項目	位置	編號	D	E	R	U	損壞位置	劣化類型	
帽梁			1	1	1	1		water seepage	
建議維修工法							數量	單位	單價
混凝土修復							2	處	

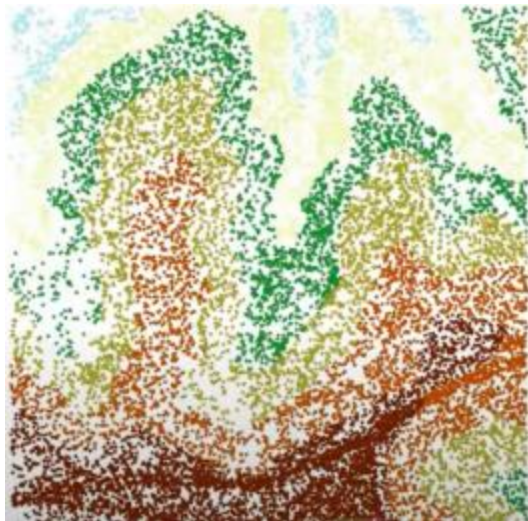


# Remote Sensing Application for Landslide Susceptibility Analysis

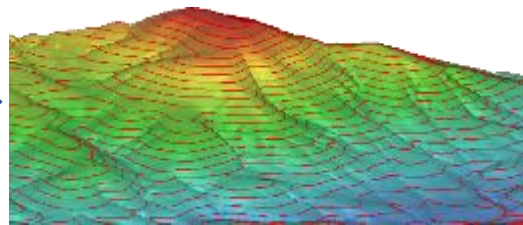


# 03 Landslide Susceptibility Analysis

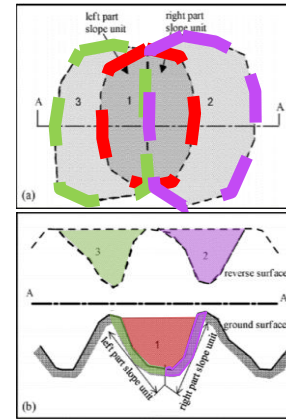
□ Lidar derived : DEM 、 Slope 、 Aspect 、 Profile curvature



Point cloud from LiDAR

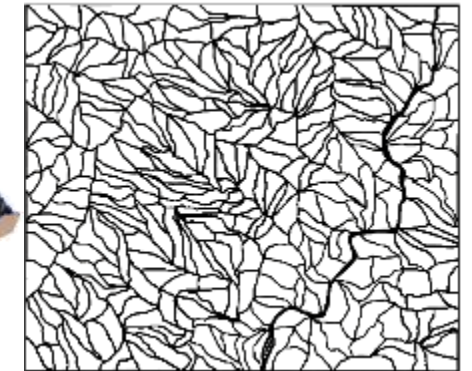
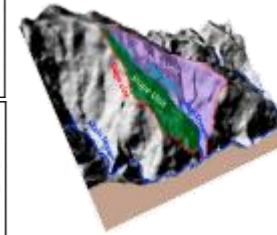


DEM



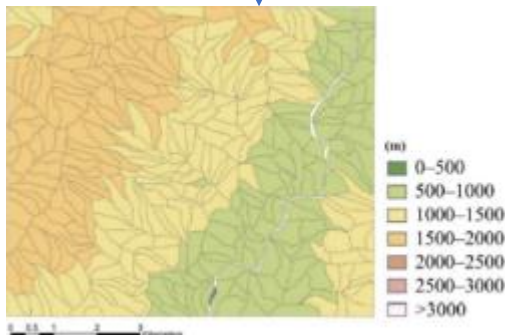
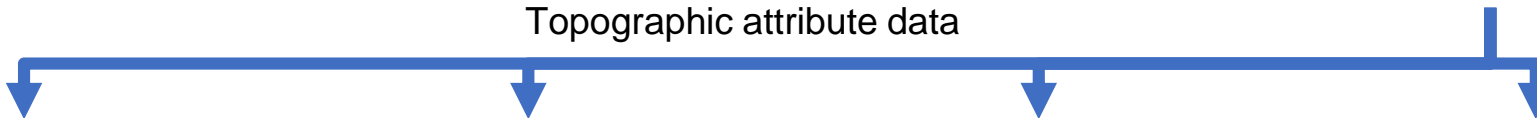
Overlap method of catchment areas(Xie et al.

2004)  
Defining the minimal unit of slope by drainage system

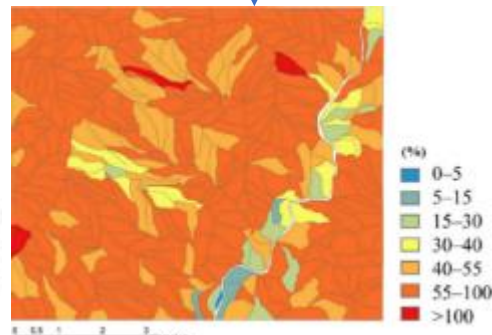


Unit of 3D slope (Tsai et al., 2019)

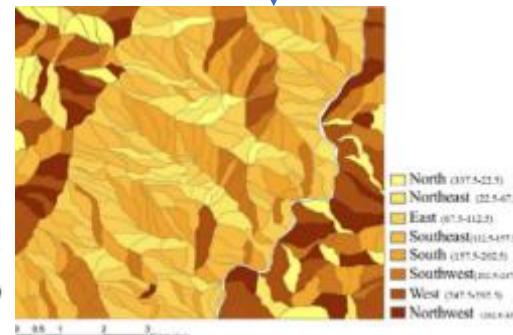
Topographic attribute data



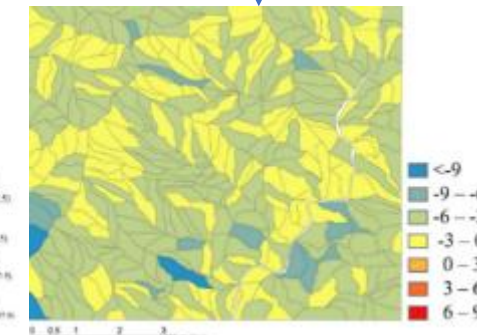
Elevation



Slope



Aspect



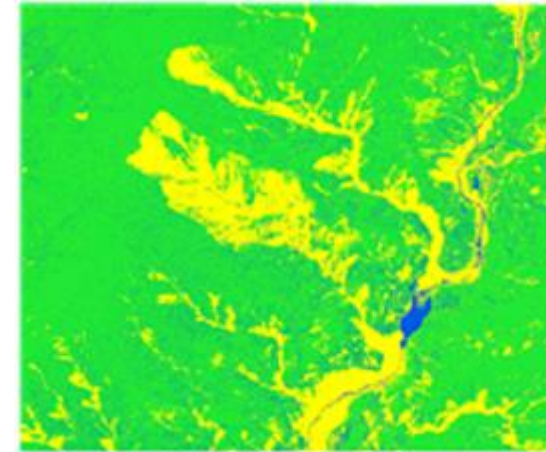
Profile curvature

# 03 Landslide Susceptibility Analysis

□ SPOT image derived land cover factors.



Maximal likelihood classification



Land cover  
 ■ Bare land  
 ■ Vegetation  
 ■ Water

## SPOT -6、7

Launching time : 2012、2014

Owner: AIRBUS

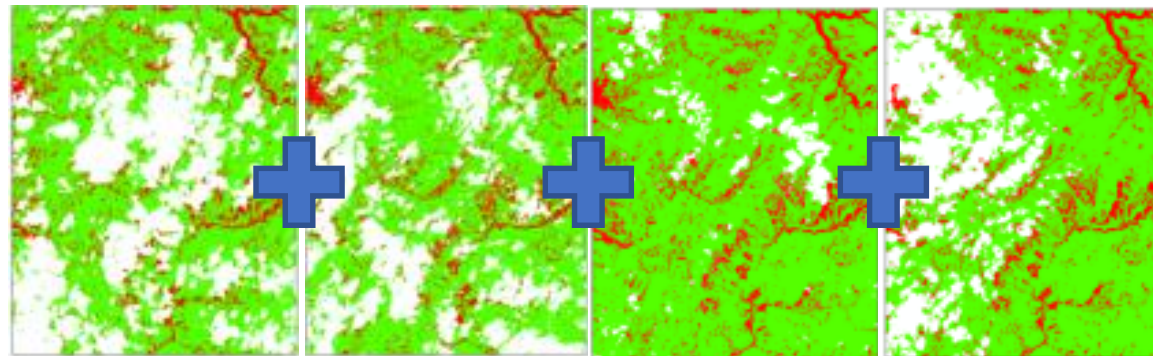
Payload: B, G, R, NIR,

Resolution: 6 m, 1.5 m

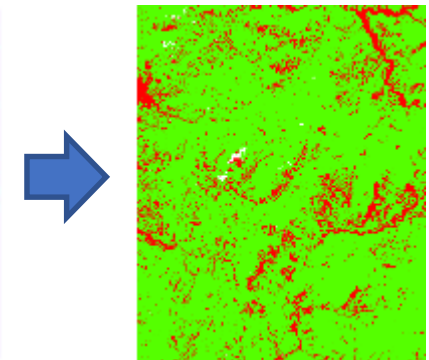
Image sheet: 60 km

Cycling time: 1-3 days

Fusion of adjacent cloudy images

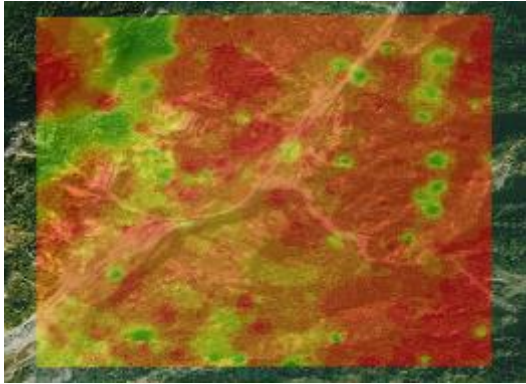


Cloud-free image

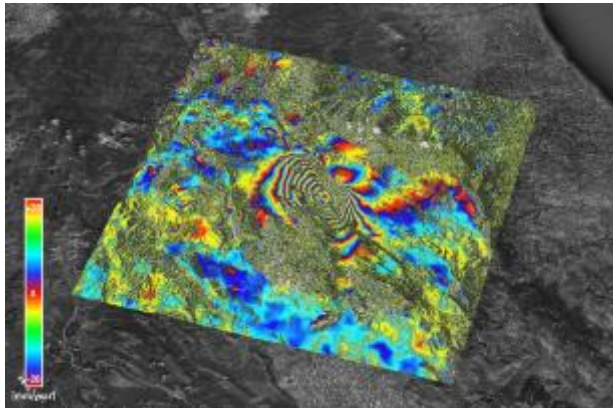




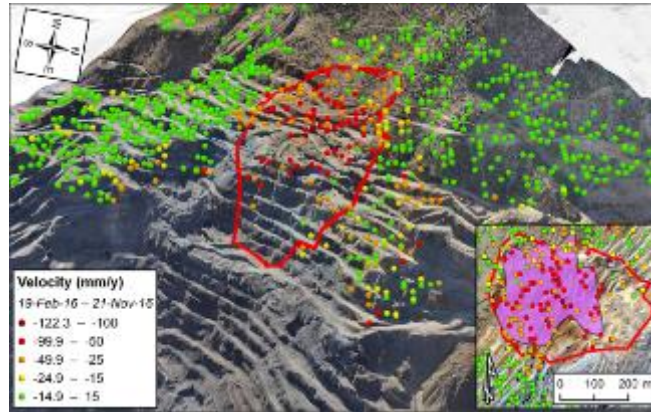
## □ InSAR-derived ground velocity gradient :



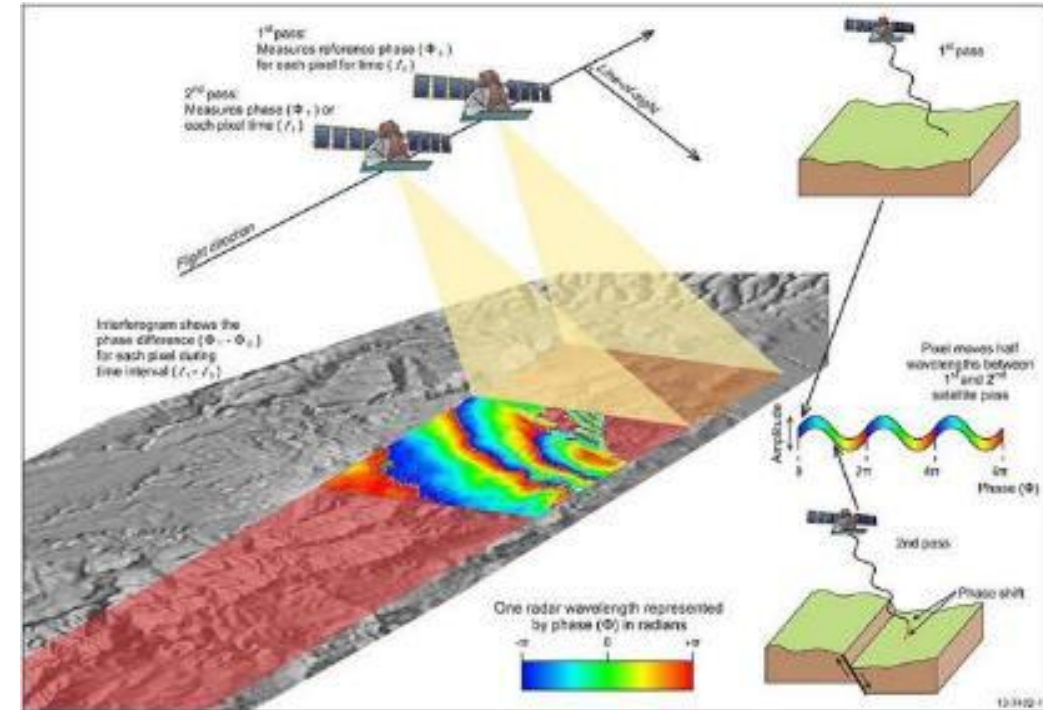
Ground velocity gradient



SAR images



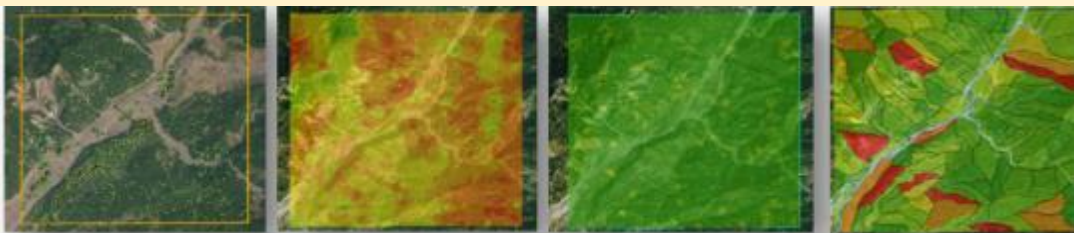
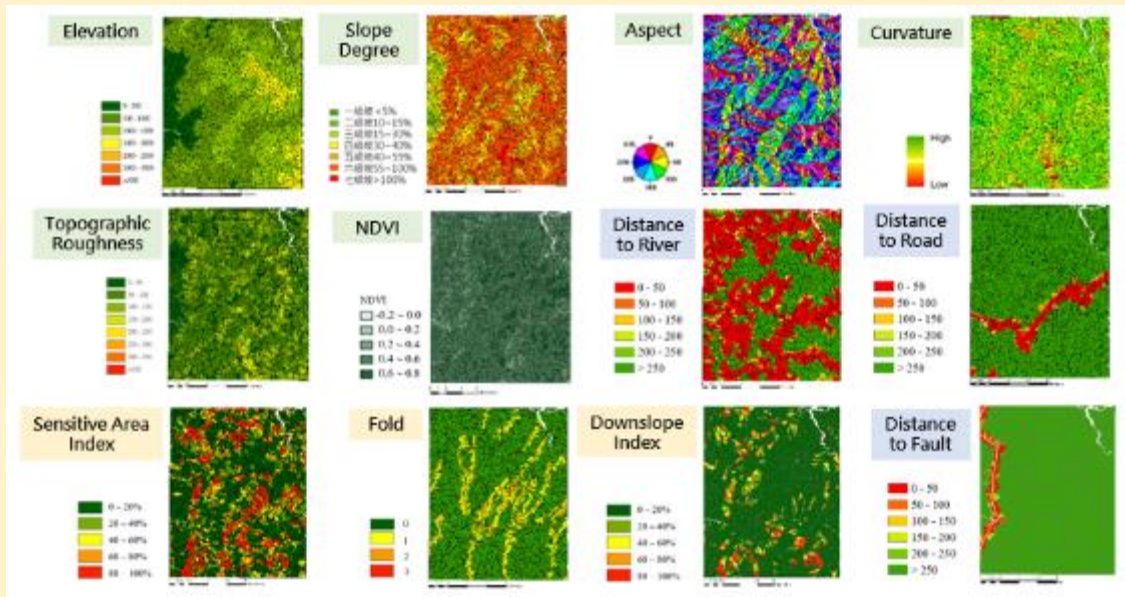
InSAR-derived displacement



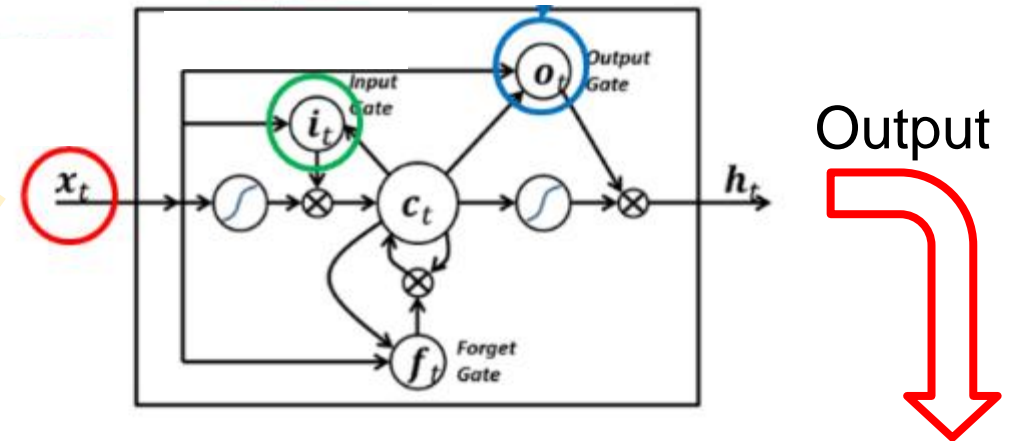
# 03 Landslide Susceptibility Analysis

## Multiple factors + Machine Learning Algorithms

### Multiple factors



InSAR-derived factor

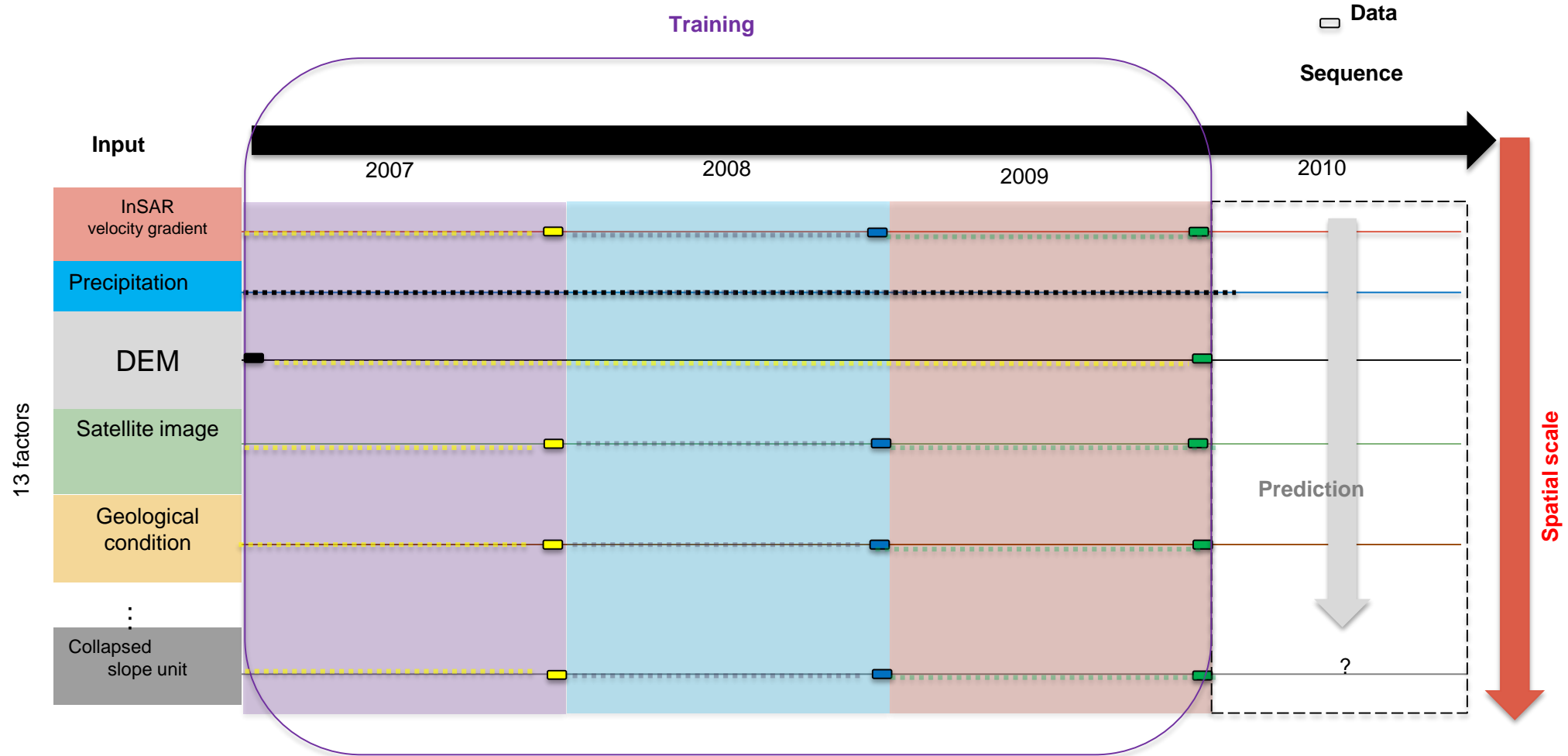


Landslide Potential	AI
High	Ai
High-middle	Bi
Middle	Ci
Low	Di

\*\*i = initial


# 03 Landslide Susceptibility Analysis

- InSAR complements the low update rate of traditional map data.

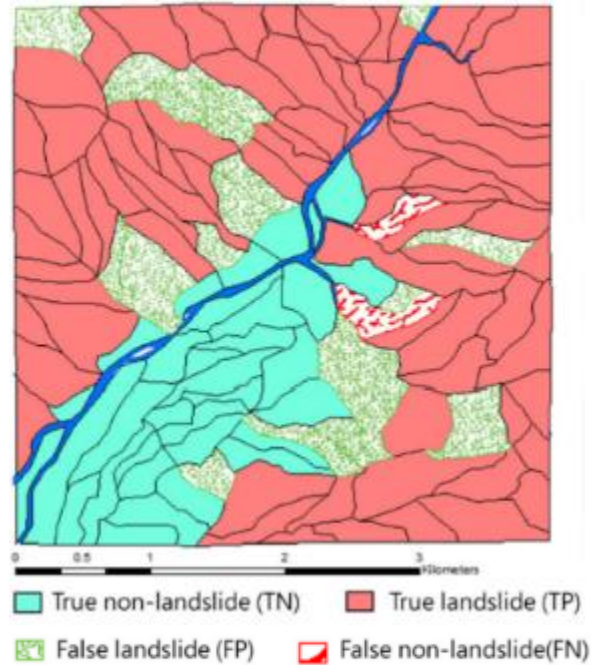


## Case study-Siaolin Village (prediction results)



 Predicted landslide area for 2010 based on training data between 2007~2009.

Accuracy evaluation



 Actual landslide area in 2010

Average prediction accuracies before and after including InSAR data in different ML methods

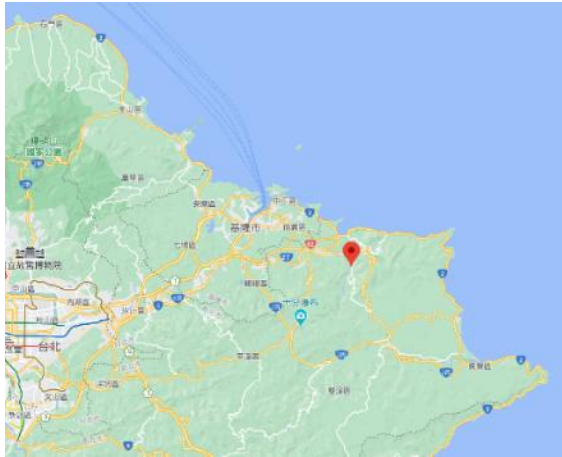
ML	Siaolin Village	
	With InSAR (%)	Without InSAR (%)
Naive Bayes	70.93	70.85
DT	68.02	62.02
Random Forest	82.95	79.84
AdaBoost	78.49	77.52
XGBoost	79.31	75.97

Up to 8% improvement if InSAR data is used.

# Model extension- Houtong case

## Case location

WGS84 : 25.097207,



(source: google map)

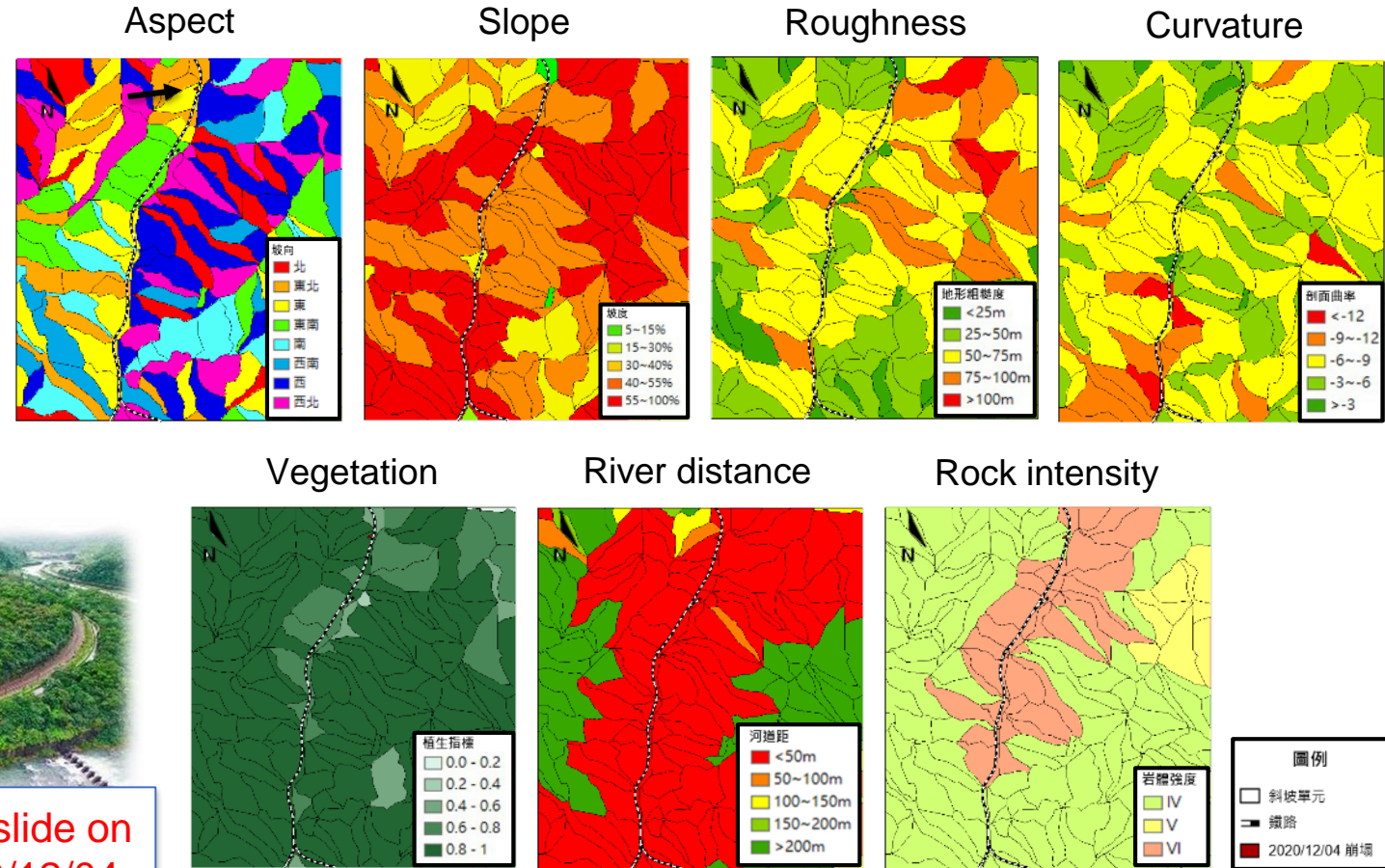


(source: MOTC)

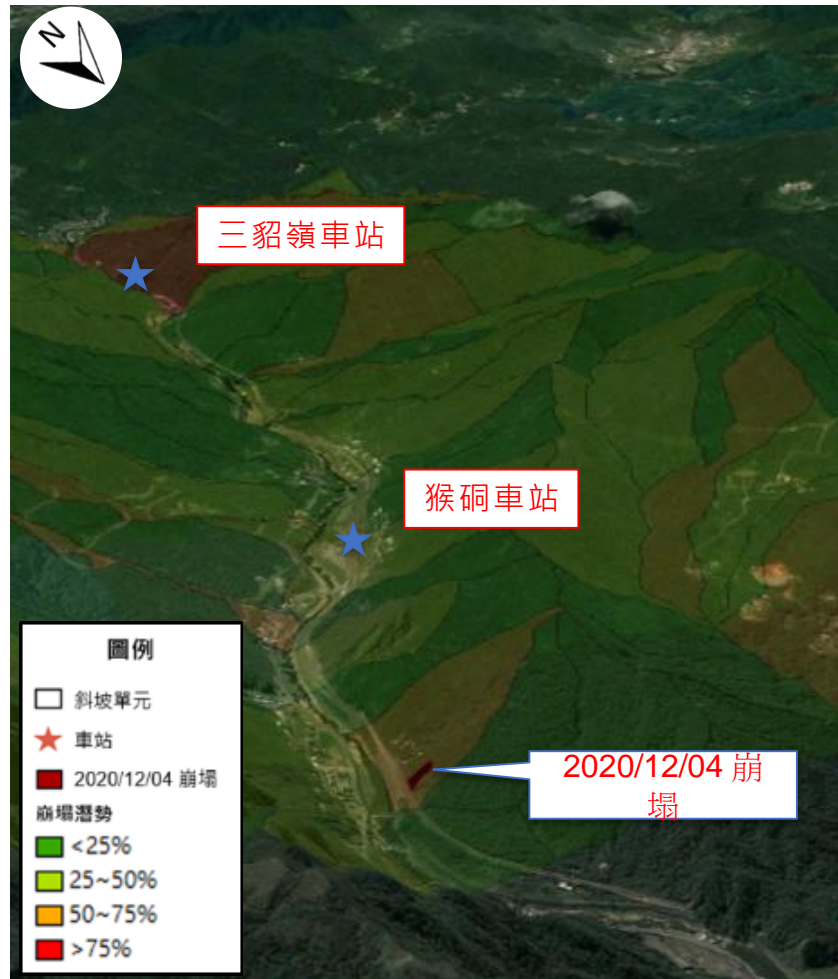


Landslide on 2020/12/04

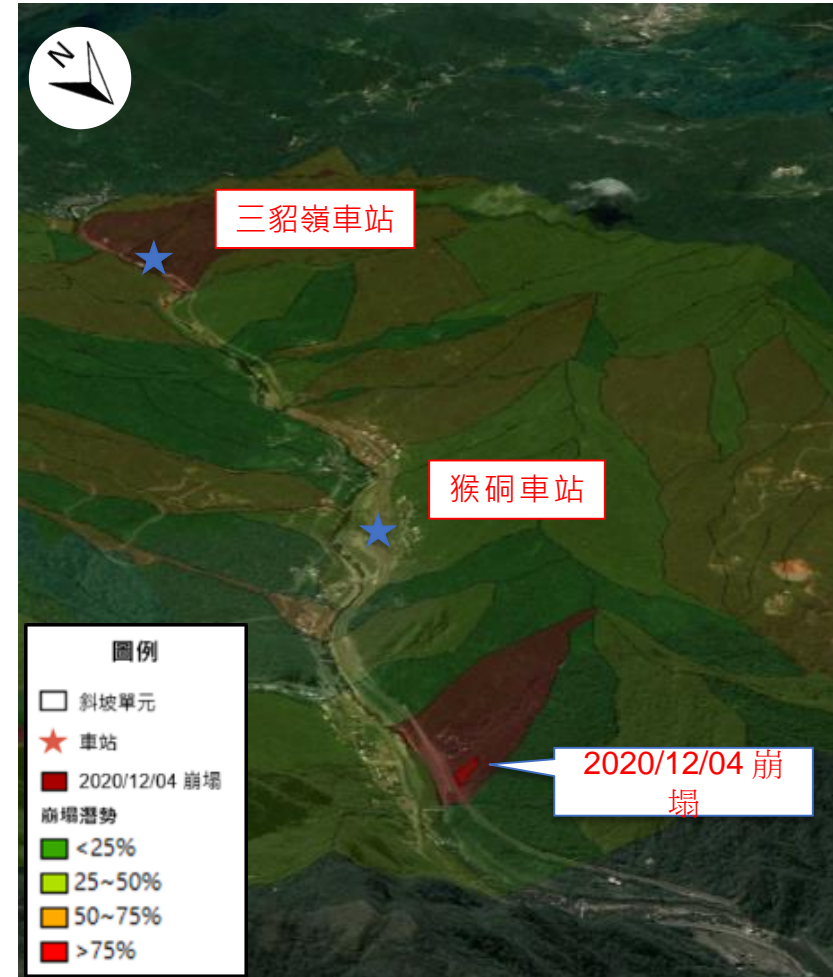
Applying the previously developed ML model using local data in another case.



Prediction results for Houtong based on the model developed for Siaolin Village



Mid-to-high landslide potential (before using InSAR)

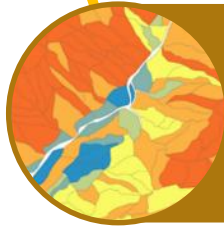


High landslide potential (after including InSAR)

# Conclusions



Modern remote sensing technology enables an accurate and efficient acquisition of multiple spatial data for a wide area.



Various information can be automatically extracted from these remotely sensed data using AI techniques.



AI technique contributes to the optimal use of all available data so that the complicated mechanism of a subject can be better analyzed and modeled.



With the improved accuracy and efficiency of analysis model, physical problems can be better solved, contributing to our knowledge of the real world.

# Conclusions

Mobile platform (UAV, Air plane, Satellite)  
Multiple Sensing

+ Accurate and efficient analysis  
( AI )

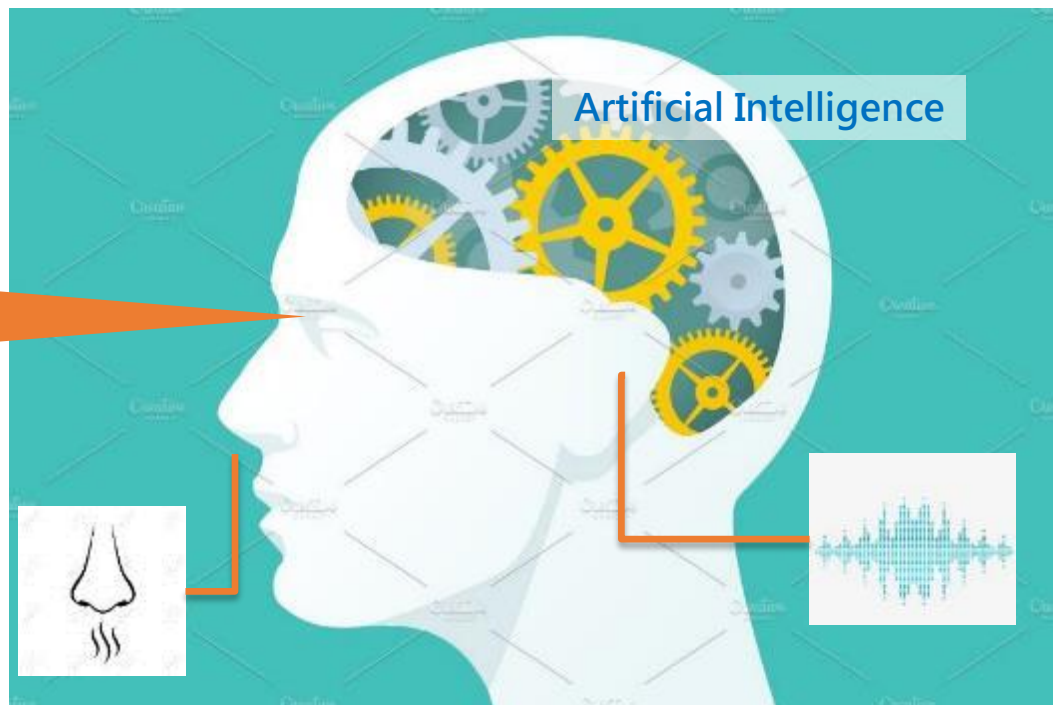
→ Super power to kill problems



聰明 = 耳聰目明



Sensing



UAV, air plane, satellite





**感謝聆聽**